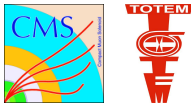


Proton reconstruction with the TOTEM Roman pot detectors for high- β^* LHC data



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ABSTRACT: The TOTEM Roman pot detectors are used to reconstruct the transverse momentum of scattered protons and to estimate the transverse location of the primary interaction. This paper presents new methods of track reconstruction, measurements of strip-level detection efficiencies, cross-checks of the LHC beam optics, and detector alignment techniques, along with their application in the selection of signal collision events. The track reconstruction is performed by exploiting hit cluster information through a novel method using a common polygonal area in the intercept-slope plane. The technique is applied in the relative alignment of detector layers with μm precision. A tag-and-probe method is used to extract strip-level detection efficiencies. The alignment of the Roman pot system is performed through time-dependent adjustments, resulting in a position accuracy of $3\text{ }\mu\text{m}$ in the horizontal and $60\text{ }\mu\text{m}$ in the vertical directions. The goal is to provide an optimal reconstruction tool for central exclusive physics analyses based on the high- β^* data-taking period at $\sqrt{s} = 13\text{ TeV}$ in 2018.

KEYWORDS: Pattern recognition, cluster finding, calibration and fitting methods; Performance of High Energy Physics Detectors

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1 Introduction

Elastic and diffractive interactions of high-energy protons at the CERN LHC are characterised by scattered protons emerging at small angles (microradians) with respect to the beam direction. These protons can be measured with detectors that are inserted into the beam pipe called “Roman pots” (RPs), which are movable near-beam devices that allow the detectors to be brought very close (down to a few mm) to the beam without affecting the vacuum, beam stability, or other aspects of accelerator operations.

This paper describes methods for the reconstruction of the scattered proton trajectories in such near-beam detectors. These reconstruction techniques have been developed by the CMS and TOTEM Collaborations for the studies of central exclusive hadron production [1–3], where in addition to the two scattered protons, a central system of particles is created. This paper is based on data jointly taken by the CMS and TOTEM detectors in a special, low instantaneous luminosity run in July 2018, at the proton-proton (pp) centre-of-mass energy of 13 TeV, with an integrated luminosity of 4.7 pb^{-1} [4].

The acceptance of the RP detector system for elastically or diffractively scattered protons is determined by the beam optics configuration.

With the high- β^* setting, the beam divergence is small. Here β^* denotes the value of the amplitude function at the interaction point (IP), often referred to as the distance from the IP where the beam width doubles [5]. The forward detectors, a few hundred metres away from the interaction point and within millimetres from the outgoing beam, are able to measure the scattered protons at microradian angles and sub-GeV transverse momenta. The acceptance as a function of the squared four-momentum transfer of the protons (t) starts at -0.03 GeV^2 . The proton kinematic properties are determined from the proton scattering angle, independently of the momentum loss if the latter is small. Protons with fractional momentum loss up to 20% can be observed, with wide acceptance for the invariant mass of the created central hadron system [1, 2].

The present paper covers subjects ranging from signal clustering in the silicon microstrip detectors used in the RPs, to the reconstruction of proton tracks, the cross-check of the beam optics, and the alignment with respect to the beam line. The aim is to measure the scattered proton momentum and the location of the primary interaction for central exclusive physics events [6]. Improvements relative to earlier methods are presented for the selection and analysis of signal events, specifically for the precise momentum balance of forward protons with centrally produced particles. Several of the discussed techniques are relevant to other beam optics settings as well.

The paper is organised as follows. An overview of the LHC beam parameters and the RP detectors is given in section 2, along with some considerations on the scattered proton trajectory, and details of the data set used. The reconstruction of the proton hit locations within the RPs is discussed in section 3, including pattern recognition and matching, relative alignment of the detector layers, extraction of the strip hit efficiencies, and determination of the correction factors. The reconstruction of the full proton trajectory is detailed next (section 4), together with a discussion of the cross-checks of the beam optics, the distributions of the interaction point locations and scattering angles, and the absolute alignment of the RPs. Results on momentum resolution and applications for event classification and selection for physics analyses are also shown. The paper ends with a summary in section 5.

2 The CMS and TOTEM detectors

We use a right-handed coordinate system, with the origin at the nominal collision point, the x axis pointing to the centre of the LHC ring, the y axis pointing up (perpendicular to the LHC plane), and the z axis along the anti-clockwise beam direction.

2.1 The LHC beam parameters

In this low instantaneous luminosity data-taking period, the β^* values in the horizontal and vertical directions are $\beta_x^* = 45 \text{ m}$ and $\beta_y^* = 90 \text{ m}$, respectively. The initial normalised emittance is in the range $\varepsilon_n = 1.2\text{--}1.6 \text{ }\mu\text{m}$ [7]. The half-crossing angle in the horizontal plane is $60 \text{ }\mu\text{rad}$. At the nominal IP, the transverse size of the beam is $\sigma = \sqrt{\varepsilon\beta^*}$ and the angular beam size (beam divergence) is $\sigma' = \sqrt{\varepsilon/\beta^*}$, where the emittance ε is related to the normalised emittance as $\varepsilon_n = \varepsilon\beta\gamma$. Here β is the ratio of the velocity of the beam particles to the speed of light, and γ is the Lorentz factor. Given the beam energy of $p_{\text{beam}} = 6500 \text{ GeV}$, we have $\beta\gamma \approx 6930$ and the expected value of the emittance is $\varepsilon \approx 0.2 \text{ nm}$. The transverse momentum spread is $\sigma_{p_{x/y}} = p_{\text{beam}}\sigma'_{x/y}$. Table 1 summarises the relevant beam parameters.

The transverse size of the beam spot (BS) can be calculated from the beam width as $\sigma^{\text{BS}} = \sigma/\sqrt{2}$. The size of the beam spot is measured by using reconstructed interaction vertices with tracks in the

central silicon tracker of the CMS detector [8]. It slowly increases within an LHC fill from 70 to 110 μm in x , and from 90 to 110 μm in the y direction. With an assumed average initial normalised emittance $\varepsilon_n \approx 1.4 \mu\text{m}$ we expect in the horizontal direction $\sigma_x^{\text{BS}} \approx 65 \mu\text{m}$, $\sigma'_x \approx 2.1 \mu\text{rad}$, $\sigma_{p_x} \approx 14 \text{ MeV}$, and in the vertical direction $\sigma_y^{\text{BS}} \approx 95 \mu\text{m}$, $\sigma'_y \approx 1.5 \mu\text{rad}$, $\sigma_{p_y} \approx 10 \text{ MeV}$. Both the measured horizontal and vertical initial beam spot width values are close to their expectations (70 and 90 μm).

Table 1. The beam parameters and related quantities at the CMS interaction point for the $\beta^* = 90 \text{ m}$ run at $\sqrt{s} = 13 \text{ TeV}$ in 2018.

Beam parameter	Value
Horizontal amplitude function at IP, β_x^*	45 m
Vertical amplitude function at IP, β_y^*	90 m
Normalised emittance (expected), ε_n	1.2–1.6 μm
Horizontal beam spot width (measured), σ_x^{BS}	70–110 μm
Vertical beam spot width (measured), σ_y^{BS}	90–110 μm
Half of horizontal crossing angle	60 μrad

2.2 Roman pot detectors

The intersection points of the LHC are numbered from 1 to 8. The CMS detector operates at interaction point 5, and the adjacent LHC sectors are referred to as “45” and “56”. The proton spectrometer of the TOTEM experiment consists of two telescope arms, referred to as “Arm 1” (in sector 45) and “Arm 2” (in sector 56) for positive and negative pseudorapidities, respectively [9, 10]. In each arm there are two stations located at about $\pm 213 \text{ m}$ (near) and $\pm 220 \text{ m}$ (far) relative to the nominal IP (figure 1). Each station consists of two units. Only the units with vertical pots are considered in this paper. Each unit has two RPs, one located above (“top” or T), and one below (“bottom” or B) the LHC beam. The names of the RP detector layer groups are given in table 2 and figure 2 (left panel). The term “parallel” refers to cases where both RP detectors above or below the beamline (top-top or TT, bottom-bottom or BB) have signals above predefined thresholds, whereas the “diagonal” configuration refers to the other two cases (top-bottom or TB, bottom-top or BT).

An RP contains ten layers of silicon strip detectors, placed alternately in two orthogonal orientations (u and v) with five layers in each. The strips are directed at 45° with respect to the vertical (y) axis for the far pots (figure 2, right), and at 37° or 53° for the near pots. The layers can approach

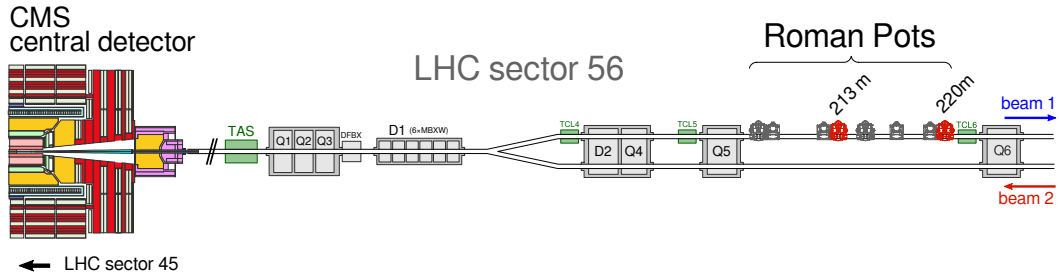


Figure 1. Plan view of LHC section 56 (Arm 2) close to CMS (point 5 at the LHC). The location of the near and far Roman pots of Arm 2 are indicated in red. Also, various magnetic beam elements (dipoles D1 and 2, quadrupoles Q1 to Q6) as well as other Roman pots not used for this paper are shown.

Table 2. The naming of the various RP layer groups.

Arm	Location	Vertical position	Proj.	Name	Arm	Location	Vertical position	Proj.	Name
1	near	top	u	1nTu	2	near	top	u	2nTu
1	near	top	v	1nTv	2	near	top	v	2nTv
1	near	bottom	u	1nBu	2	near	bottom	u	2nBu
1	near	bottom	v	1nBv	2	near	bottom	v	2nBv
1	far	top	u	1fTu	2	far	top	u	2fTu
1	far	top	v	1fTv	2	far	top	v	2fTv
1	far	bottom	u	1fBu	2	far	bottom	u	2fBu
1	far	bottom	v	1fBv	2	far	bottom	v	2fBv

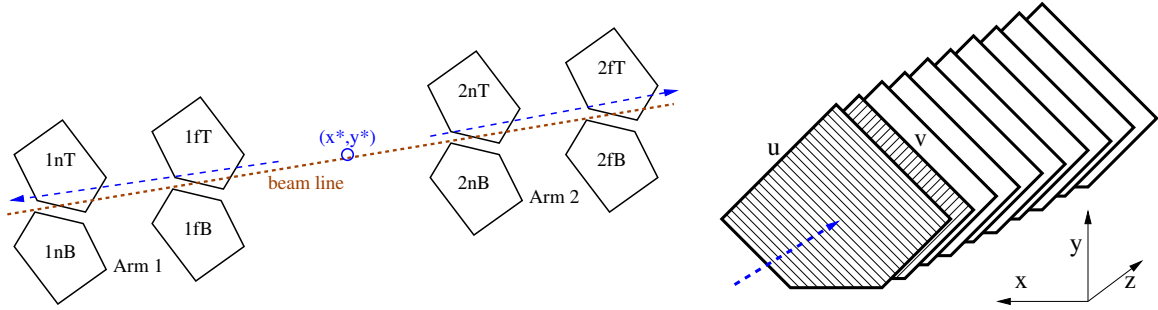


Figure 2. Left: The eight RP units in Arm 1 and Arm 2 with the beam line, along with the location (x^*, y^*) of the primary interaction and two proton trajectories (dashed blue arrows), not to scale. Right: An RP unit comprising 10 layers with strips oriented alternately in the u and v directions. The blue dashed arrow represents an incoming proton. The axes of the local coordinate system are indicated with black solid arrows.

the beam at a distance of a few millimetres without affecting the LHC operation (they are retracted before each beam injection and inserted again afterwards).

Schematic displays of some events with hits and projections of reconstructed local straight tracks, called “tracklets”, in RPs are displayed in figure 3. Normally, the scattered protons are detected by both the near and far pots, yielding a total of four tracklets. Events with more than four tracklets, pointing to energetic secondaries or multiple simultaneous primary pp collisions, are excluded from the analysis. The RPs share a common readout with the CMS detector.

2.3 Proton trajectory

Once the scattered protons leave the interaction region, they traverse the magnetic fields created by the CMS solenoid and the LHC beam magnets until most of them reach the first and then the second RP stations. During their flight, such protons do not traverse the beam pipe. The RP stations have their own secondary vacuum, separated by a 300 μm thin steel window from the primary LHC vacuum, and they are in a region where the magnetic field is zero. Of course, to determine the scattered proton kinematics the inhomogeneous magnetic fields due to the sequence of several quadrupole and dipole magnets need to be modelled.

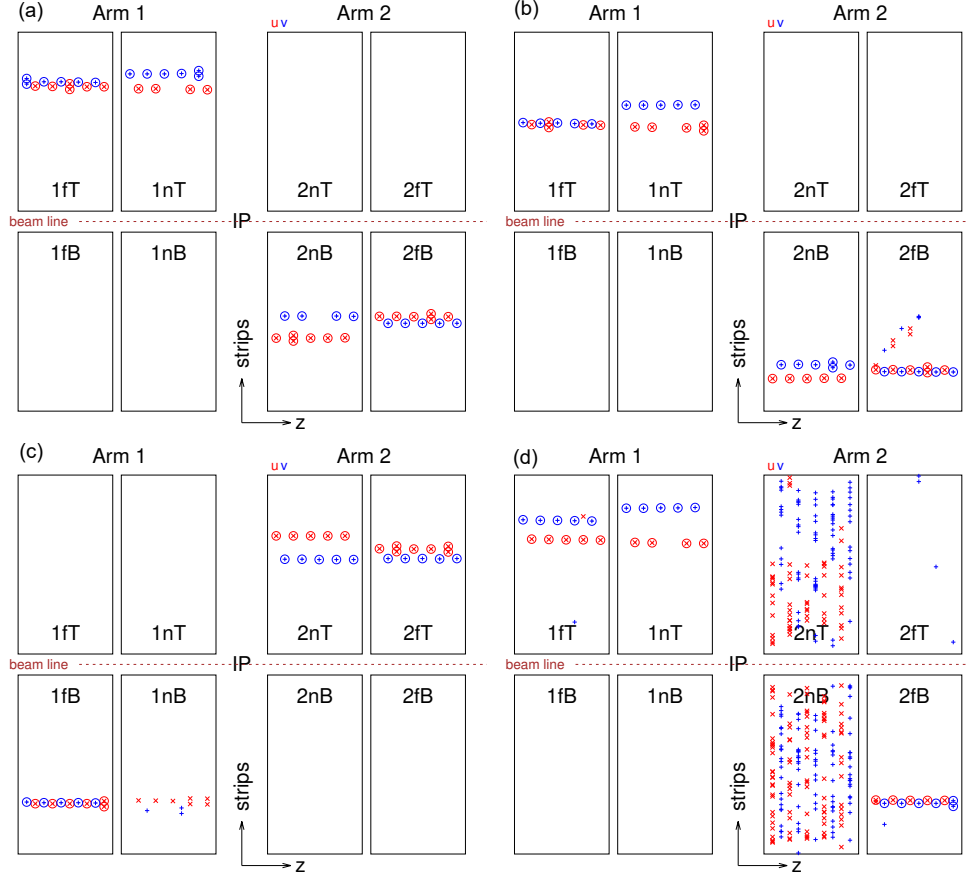


Figure 3. Schematic displays of four events with hits and projections of reconstructed local tracks (tracklets) in RPs, with outlines of Arm 1 and 2, near and far, upper and lower plots (not to scale). Strips of reconstructed clusters in u and v layers are plotted with red x and blue $+$ markers, respectively. Two vertically adjacent symbols represent a two-strip cluster. Reconstructed clusters on a found tracklet are marked with circles. From left to right and from top to bottom: (a) normal event, (b) normal event with additional secondary particles; (c) not reconstructed event (less than three hits in the v orientation of 1n); (d) not reconstructed event (hadronic interaction in some beam element before 2n).

The effects of multiple scattering and nuclear collisions in the detector material and in the stainless steel window that separates the LHC primary vacuum from the RP secondary vacuum, need to be considered. The sensitive detector elements are silicon layers with a thickness $d = 300 \mu\text{m}$. Silicon (steel) has a radiation length $X_0 = 9.370$ (1.757) cm, and a nuclear collision length $\lambda = 30.16$ (10.37) cm. For multiple scattering within one layer, the standard deviation of the scattering angle, in a Gaussian approximation [11], is given by $\theta_0 \approx 13.6 \text{ MeV}/(\beta c p) \times z \sqrt{d/X_0}$, where z is the charge number of the incident particle, and we have neglected the logarithmic correction. With the proton momentum $p = 6500 \text{ GeV}$, we get $\theta_0 \approx 0.12$ (0.27) μrad for the silicon (steel) layer. Within an RP, assuming 9 detector planes, after a distance of 36 mm between the first and the last layer, the average resulting shift is 15 nm, and is neglected. After 10 scattering planes and a distance of 7 m between two pots, the shift is 3 μm , which again is neglected. The probability of a nuclear collision within a silicon (steel) layer is $d/\lambda \approx 10^{-3}$ (3×10^{-3}). In the case of an RP with two thin windows and 10 layers, it adds up to 1.6%. The nuclear collisions thus contribute to the tails of the hit location distributions.

2.4 The data set

In the high- β^* data-taking period considered here, the average number of pp collisions per bunch crossing is small (0.1–0.3), and for the same reason the collected integrated luminosity is limited. For this data set, the Level 1 (hardware) trigger requires detected protons in the far RPs in each arm, in parallel or diagonal configurations (section 2.2). Triggering is based on “trigger roads”, groups of 32 consecutive silicon strips. The trigger bit is set if trigger roads at the same location have signals above a predefined threshold in several detector layers. The elastic pp cross section is much larger than that of central exclusive production events, and therefore the available bandwidth of the data acquisition system would be saturated. Suitable combinations of the trigger bits from the RPs are used to reject elastic events. The high-level trigger has multiple components [12]; the pixel and track activity filters of the CMS silicon tracker system require hits or tracks from centrally produced charged particles.

For these studies two data sets are used. One data set with no centrally reconstructed charged particles (“0-track” data set with some unrelated hits in the pixel detector) contains 39 million events of which 29 million have all four tracklets reconstructed. The other data set has two oppositely-charged centrally reconstructed particles (“2-track” data set) contains 119 million events of which 88 million have all four tracklets reconstructed.

3 Tracklet reconstruction

In various exclusive physics analyses, the classification of signal events is based on the conservation of momentum between the incoming and outgoing particles. To maximise the selection efficiency, an optimisation of the standard local tracklet reconstruction [9, 10] was performed, which led to improvements of resolution and uncertainty estimations.

Every RP detector layer contains 512 strips, each with a width (pitch) of 66 μm . A hit cluster is a group of adjacent strips, each with a collected charge above a certain threshold. Most of the clusters are one-strip wide, with the hit in the central area of the strip. The less frequent two-strip clusters arise through drifting and diffusing electrons from hits in the region between two strips (e.g. in panel (a) of figure 3, Arm 1, 1nT). The fraction of two-strip clusters for each detector layer is shown in figure 4, in groups of similarly oriented layers (layer groups). The result of a Gaussian fit is also indicated, with a mean $f_2 = 10.5\%$. The outliers, mostly at smaller values, belong to layers with low strip-level efficiencies. Two-strip clusters carry important information and provide better spatial resolution than

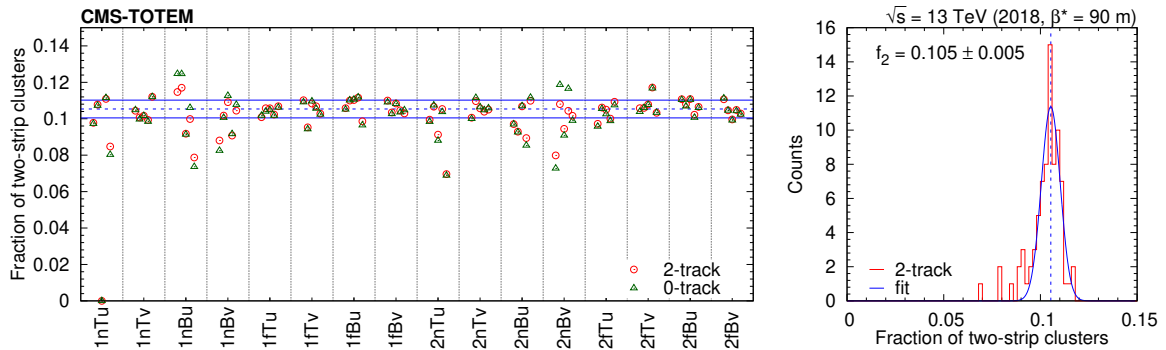


Figure 4. Left: Fraction of two-strip clusters for each detector layer, in groups of similarly oriented layers. Right: Distribution of the fraction of two-strip clusters with the result of a Gaussian fit.

one-strip clusters (section 3.1). Clusters with three or more strips are rare, with a rate below half a percent, demonstrating that the effect of capacitive coupling between neighbouring strips is negligible.

Lacking an analog strip readout, the location of a cluster cannot be computed using a charge-weighted cluster mean. Hence the location of a one-strip cluster can be associated to an integer number s_i , whereas the location of two-strip cluster is the average of their integer numbers (half-integer).

3.1 Pattern recognition

In conventional applications, track finding usually starts with local hit reconstruction that, in case of segmented detectors, also includes cluster finding. Based on the hits found, track seeds (compatible hit multiplets) are built. These are used as starting points for a global track finding by extending them towards other detector layers and picking up free, unused hits (through a Kalman filtering method [13, 14]). Finally, the track candidates are scanned for split or multiply reconstructed trajectories, their momentum vectors are determined, and they are used to fit a common global event vertex. The calibration of a tracking detector includes its alignment by means of cosmic ray muons or particles originating from particle collisions, but sometimes also implies a gain calibration. The performance of a tracking system is usually characterised by its position and momentum resolutions [15].

In the case of RP layers, local hit reconstruction is performed by searching for groups of contiguous strips, mostly one-strip and two-strip clusters, resulting in integer and half-integer cluster coordinates. The strips do not provide pulse height information, but only binary information based on signal discrimination. Since a cluster is a series of adjacent strips with a given width, the trajectory-hit residuals follow rectangular distributions. For this reason, instead of performing least-square fits, a different approach is chosen with the aim to use as much information as possible.

In each RP, the orientations u and v are handled separately, since the strips in the two orientations are orthogonal. The tracklet model is a straight line with local hit coordinate u_i (or v_i) in the i th layer:

$$u_i = az_i + b + \delta_i, \quad (3.1)$$

where a is the slope and z_i is the coordinate of the location of the detector layer along the beam direction. The centre of the RP is at $z = 0$ where the tracklet has the coordinate b (intercept). The misalignment of the detector layers is quantified by relative shifts δ_i (section 3.2). Common translation (all δ_i values are equal) and shear (linear relation $\delta_i = \tau_{\text{shear}} z_i$) are weak modes and are difficult to detect, and therefore the alignment is carried out with the outermost (first and fifth) layers fixed, $\delta_1 = 0$ and $\delta_5 = 0$. The z -locations of the layers for Arm 1 are 20.3, 11.3, 2.3, -6.7 , -15.7 mm (u orientation) and 15.7, 6.7, -2.3 , -11.3 , -20.3 mm (v orientation); the same values hold for Arm 2, but with opposite sign.

An ideal track traverses two pots (near and far), i.e., in total four layer groups, and each layer group can have up to five hits. Using all events in the 0-track and 2-track data sets, a database of hit location patterns is built. This database is essential for pattern matching, in connection with a tag-and-probe method [16], for precise relative alignment (section 3.2) and for the determination of individual strip hit efficiencies (section 3.3). Such a procedure employs an unbiased sample of probe objects that is used to measure the efficiency of a specific set of selection criteria. Here tracklets with at least four hits are tagged, and in each layer a hit at the expected location is searched for. In the case of layer group 1nTu, at least three hits are required since one of its layers is inefficient.

To greatly reduce the number of hit location patterns, common translation (of the first layer, s_1) and average shear are removed. Since we want to distinguish between one-strip and two-strip clusters,

only integer displacements $-[s_1]$ are applied. This way, the relative location in the first layer will be either 0 (one-strip) or 0.5 (two-strip). If the first layer is empty, the next layer with valid hit is taken as reference. The average integer shear is also removed by subtracting the value $i\langle s_i - [s_1] \rangle$ for layer i , where $\langle s_i - [s_1] \rangle$ is deduced from $\sum i(s_i - [s_1]) / \sum i$ by rounding down to an integer, where s_i is the strip number on layer i . Some examples for the final patterns are (0, 0.5, 1, 1, 2), (0, 0, -1, -3, -2), or (0.5, 1, 1, 2.5, 2). Our data sets provide a database of relative hit location patterns with about 15 thousand entries for each layer group (there are altogether 16 layer groups).

If the relative shifts δ_i are known, the predicted hit location on the i th layer is $u_i^{\text{pred}} = az_i + b + \delta_i$ in strip-width units. The hit distribution of the incoming protons is locally uniform. The incidence angles of the protons are very small, and the protons enter the silicon planes perpendicularly to the planes. If the proton hit is closer than w to the boundary line between two adjacent strips, it deposits enough energy, such that both strips collect charge above threshold: we get a two-strip cluster. Here w is measured in pitch units. If the hit is farther than that, the proton deposits a sizeable amount of charge only in one central strip, leading to a one-strip cluster. Because of the local uniformity of the incoming proton distribution, the occurrence of two- and one-strip clusters is directly proportional to the width of the areas described above. For two-strip clusters $f_2 = 2w$, hence $w \approx 0.0525$. For one-strip clusters the cluster centre u^{meas} is expected to lie closer than $1/2 - w = 0.4475$ to the hit, whereas for two-strip clusters the distance should be below w . This way, two-strip clusters provide better spatial resolution by a factor of $(1 - f_2)/f_2 \approx 8.5$ with respect to one-strip clusters. The above requirements can be written down as

$$|u^{\text{meas}} - u^{\text{pred}}| < w \quad \text{or} \quad u_i^{\text{meas}} - az_i - \delta_i - w < b < u_i^{\text{meas}} - az_i - \delta_i + w. \quad (3.2)$$

These two inequalities define a band in the intercept-slope (b - a) plane (figure 5).

Since each detector layer provides such a constraint, we look for the intersection of five bands, i.e., a polygonal area. The determination of this common area is carried out iteratively. First, the intersection of the first two bands, i.e., a parallelogram, is determined. Next, the third band is taken, and intersections of its boundary lines with the sides of the parallelogram are looked for. If such points are found, they are added to the polygon as new vertices, and the vertices that became unnecessary are removed. The process is continued until all bands are dealt with, and we end up with a polygon (a_j, b_j) of $j = 1, \dots, n$ vertices. All points within this final polygon are equally probable and valid. The best value and variance of the intercept are represented through the centroid and the moment of inertia of the polygon [17]. Some examples for the common polygons are shown in figure 5.

In some cases such a common polygon does not exist. This can happen if there are one or more layers where the cluster centre is farther than the expected distance w from the location of the predicted hit. In such cases the above polygon method does not work: one needs to define a suitable goodness-of-fit measure. It is accomplished by means of a penalty function c : if the distance d of the predicted hit and the cluster is larger than w , we collect and sum terms $|d - w|$. Such a choice, instead of the squared difference, favours the suppression of outlier (noise or background) clusters. The minimisation of the c value in the b - a plane is accomplished by using the downhill simplex method of Nelder-Mead [18]. The minimisation usually converges in 3–5 steps, but always finds the minimum in less than 50 steps. Some examples can be seen in figure 5. In these cases the standard deviation of the measurement in the b direction is taken to be 0.3 units. This choice ensures a smooth and monotonic relation between the measured and the predicted variances of the proton momentum sum ($\sum p_x$) distributions (section 4.4, figure 22).

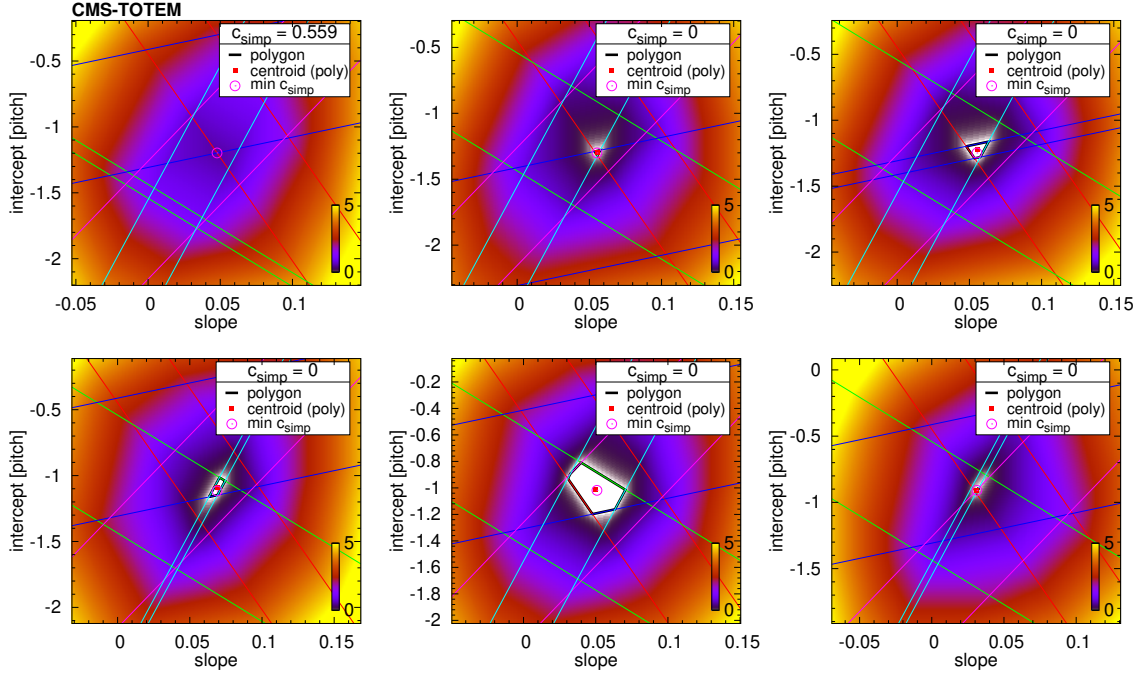


Figure 5. Examples of tracklet fits. The colour represents the value of the tracklet penalty function c in the intercept-slope (b - a) plane. Bands corresponding to individual detector layers are shown with differently coloured parallel straight lines. The intersection of these bands, if it exists, is shown as a white polygonal area ($c_{\text{simp}} = 0$) framed with thick black lines, and its centroid is marked with a red filled square. If such intersection does not exist (top left subfigure), the result of the simplex minimisation $c_{\text{simp}} > 0$ is given, and the location of the minimum indicated with a purple open circle.

3.2 Relative alignment of the detector layers

Tracklet fits can be converted into a tool to determine the relative alignment of the detector layers. The parameters of this three-dimensional problem are the relative shifts of the inner layers ($\delta_2, \delta_3, \delta_4$). The goal is to minimise the joint goodness-of-fit measure, i.e., the sum of c values for a large set of the tracklets. The employed minimisation method is again the downhill simplex method of Nelder-Mead [18]. The best δ_i values for the 16 layer groups, corresponding to the lowest sum, are displayed in figure 6. The indicated systematic uncertainties represent the region where the sum of the c values (tracklet penalty) would increase by one percent, a well-visible change. The values from the 2-track and 0-track data sets are compatible with each other. The standard deviation of the relative shifts is about 0.35, in units of strip-width. The deduced relative shifts are cross-checked with an alternative method by counting the number of tracklets with $c = 0$, giving compatible results. One-dimensional line scans around the minima are shown in figure 7.

The distribution of the joint c values for tracklets is plotted in the upper panel of figure 8. Most tracklets (89%) have $c = 0$. The distribution of the standard deviation σ_u of fitted hit location in strip-width units for the polygon method, and for the cases where the simplex minimisation was necessary, is shown in the lower panel of figure 8. The average spatial resolution is 0.10 units, i.e., about 6–7 μm . This is to be compared with the naive expectation from averaging three box distributions, $66 \mu\text{m} / \sqrt{12 \times 3} \approx 11 \mu\text{m}$, which worsens once the contribution from the standard deviation of the relative shifts ($66 \mu\text{m} \times 0.35 / \sqrt{3} \approx 13 \mu\text{m}$) is also included.

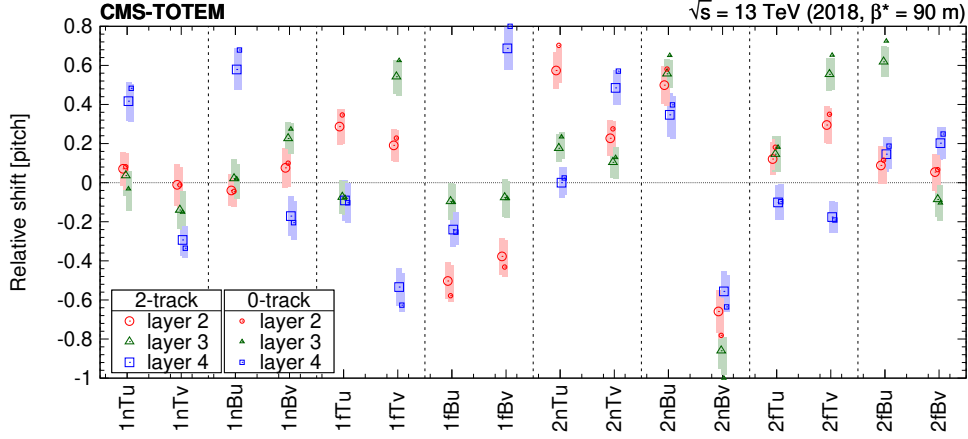


Figure 6. Deduced alignment parameters for inner layers (δ_2 — red circle, δ_3 — green triangle, δ_4 — blue square) in layer groups, in units of strip-width. Larger open symbols represent the 2-track data set, and the smaller ones are based on the 0-track data set. Shaded bars indicate the estimated systematic uncertainties (section 3.2).

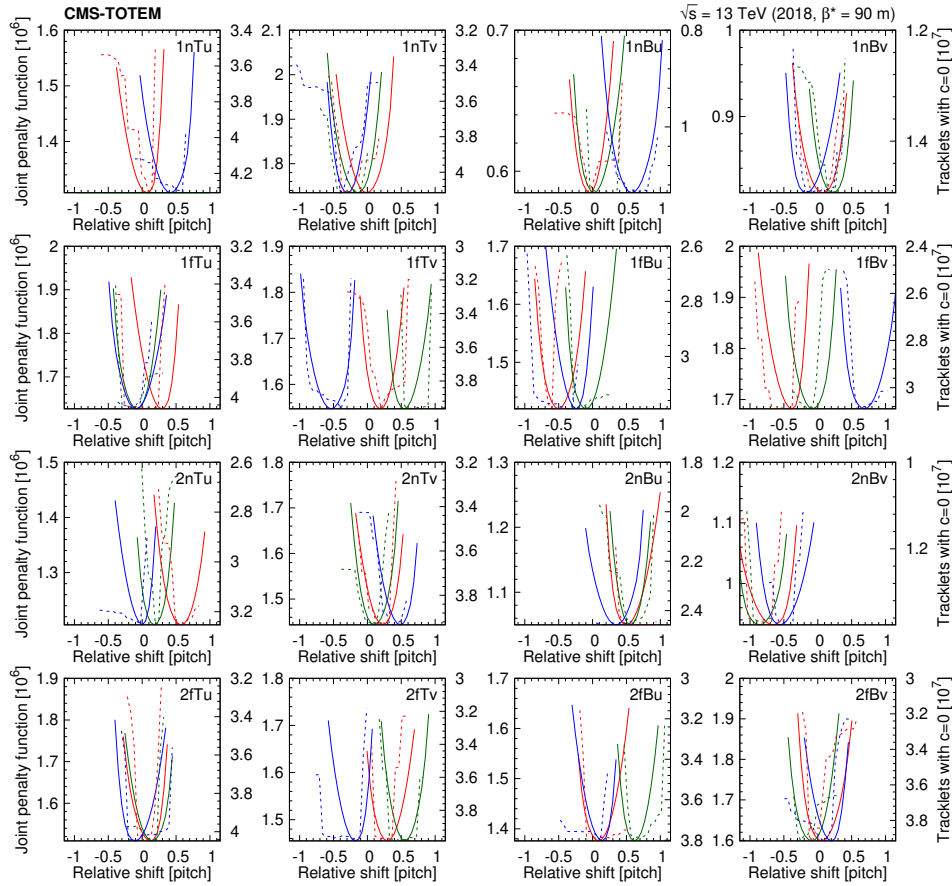


Figure 7. One-dimensional line scans of the relative shifts (δ_2 — red, δ_3 — green, δ_4 — blue) for the 16 layer groups around the best values found. The joint c value is plotted as a function of the relative shifts of the inner layers around the found minima (solid curves, left vertical scale). Goodness-of-fit from an alternative method, counting tracks with $c = 0$, is also indicated (dashed lines, right vertical scale, number of such tracks with inverted axis). In the 1nTu panel (upper left corner) the curve corresponding to the third layer is missing since that layer is inefficient.

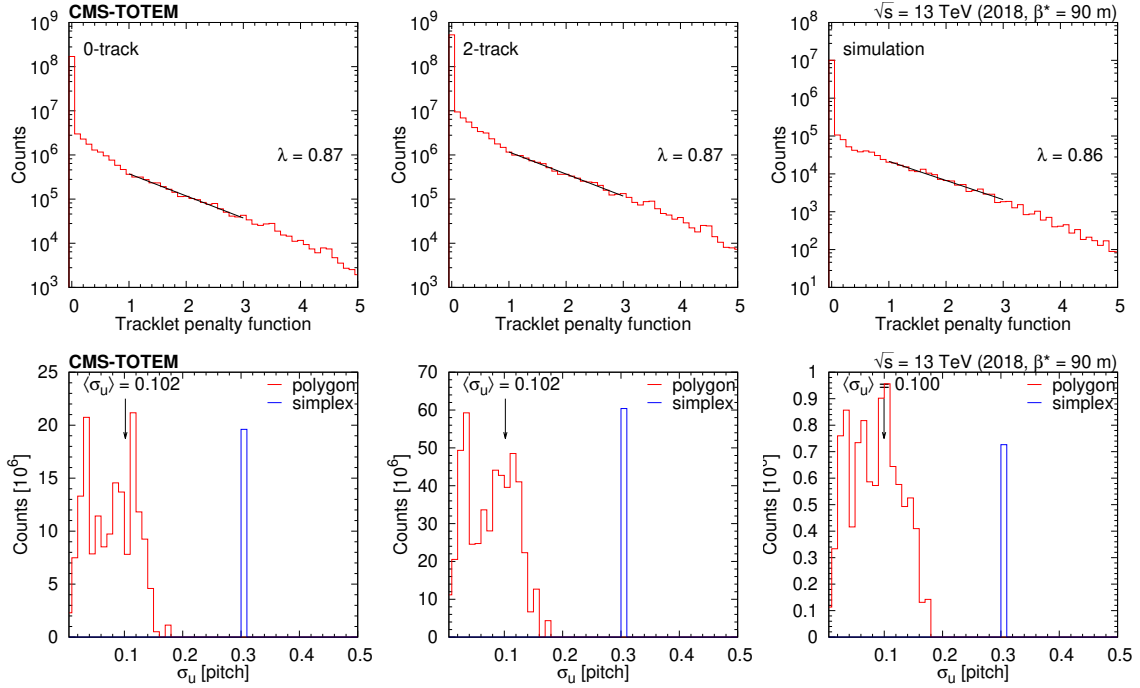


Figure 8. Upper: Distribution of the tracklet penalty function with the slope λ of an exponential fit (black line) in the range 1–3. Lower: Distribution of the standard deviation of the fitted hit location in strip-width units for the polygon method (red), and for those cases where the simplex minimisation was necessary (blue, at 0.3). The three columns correspond to the 0-track (left), 2-track (centre), and the simulated (right) data sets. The vertical arrow indicates the location of the average value.

To control and cross-check the deduced calibrations and to extract the tracklet efficiencies, a fast but realistic simulation containing one million events was set up. Tracklets are generated following a straight-line model including the non-Gaussian nature of multiple scattering, as well as the effects of nuclear collisions in the detector material. Hit creation follows the measured fraction of two-strip clusters, and takes into account the individual shifts and efficiencies. Conditions for triggering and for tracklet reconstruction are properly included. A reasonable agreement between the simulated and measured tracklet joint penalty and σ_u distributions (figure 8, right column) is achieved.

In summary, the advanced treatment just described results in better spatial and transverse momentum resolutions.

3.3 Strip hit efficiencies

The tracklet measurement is redundant since in each RP there are five layers in each orientation (u and v), but three hits are enough for triggering (using the far RPs) and for reconstruction (using all RPs). A reduced efficiency in all detector layers in an RP, as is the case in the near bottom RPs in both arms discussed below, results in tracklet detection inefficiency and a reduced proton reconstruction efficiency. In these detector layers, the inefficiency is a function of the sequential strip number in each layer and is probably caused by two factors: the instantaneous luminosity and the radiation damage accumulated during the lifetime of the detectors.

Strip-level efficiencies are extracted from the data by using the dominant hit location patterns defined below. Using the library of patterns, we count the occurrence of similar patterns where the

hit position in the given layer differs by either -2 , -1.5 , -1 , -0.5 , 0 , 0.5 , 1 , 1.5 , or 2 strip units. If the most common pattern has a frequency of more than 90% among the variants, and possesses a one-strip hit in the given layer, this pattern is called dominant.

For a tracklet with no missing hit, layers are selected one by one. If the pattern for a layer is dominant, the strip must have a hit, and the efficacy counter (n_1) for this strip is increased. For a tracklet with exactly one missing hit, the location of that hit can be predicted through the dominant pattern, and the inefficacy counter (n_0) for that strip is increased. The strip efficiency and its uncertainty are estimated using these counters.

Strip hit efficiencies extracted from the data are shown for a given layer in the 1nTv and 2nBu layer groups, and for a representative run, in figure 9. Values based on the 2-track data set and those from the 0-track data are plotted. They are compatible with each other, and the effect of their uncertainty in the proton reconstruction efficiency is about 3%. There are regions where the efficiency is rather low — especially the layer groups 1nBu, 1nBv, 2nBu, and 2nBv. These are the near bottom RPs on both sides of the IP, likely the consequence of radiation damage. Strip hit efficiencies as a function of run number, for strip #350, as an example, in layers 1–5 in various layer groups are shown in figure 10. The efficiencies are mostly constant, but for some planes they change with the run number by up to 20%.

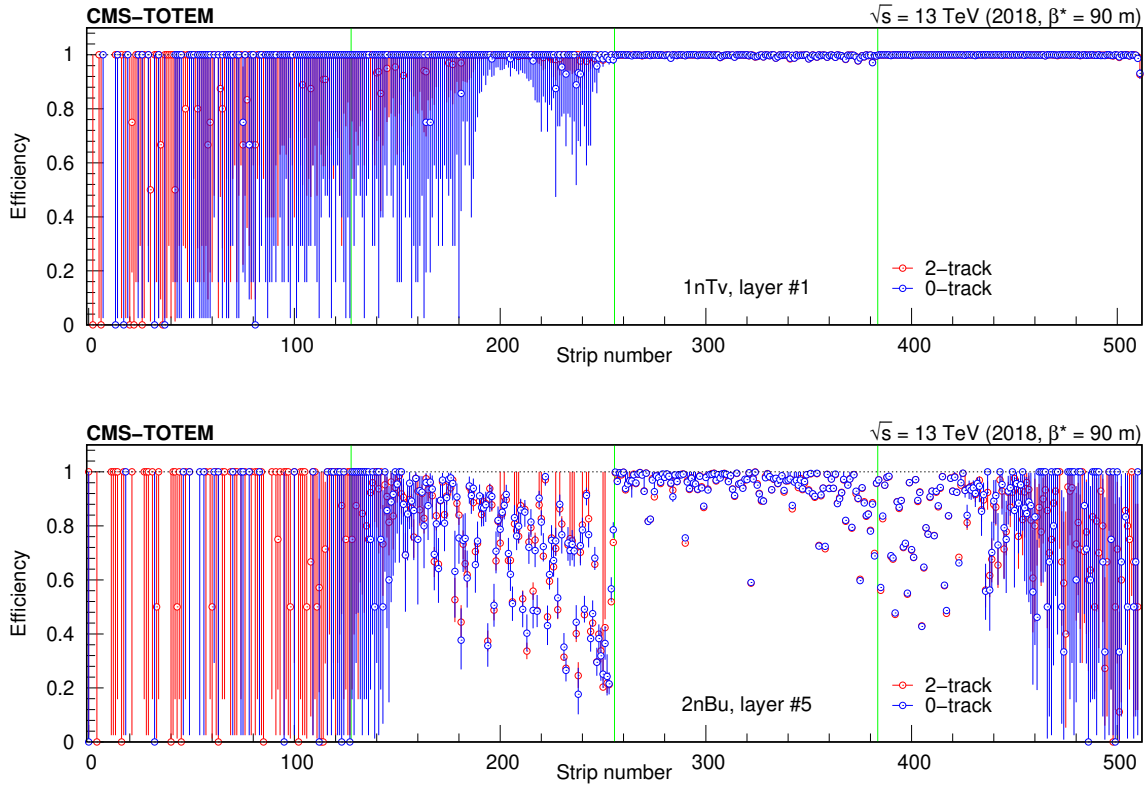


Figure 9. Strip hit efficiency from data, determined with a tag-and-probe method. Shown here are layer 5 in layer group 1nTv (top) and 2nBu (bottom) for a specific run. Values and statistical uncertainties based on the 2-track data set (red symbols) and those from 0-track data (blue symbols) are plotted. The borders of the front-end chips are indicated with (green) vertical lines. The uncertainties are large at the left or the right sides of the layers, because those regions are rarely hit.

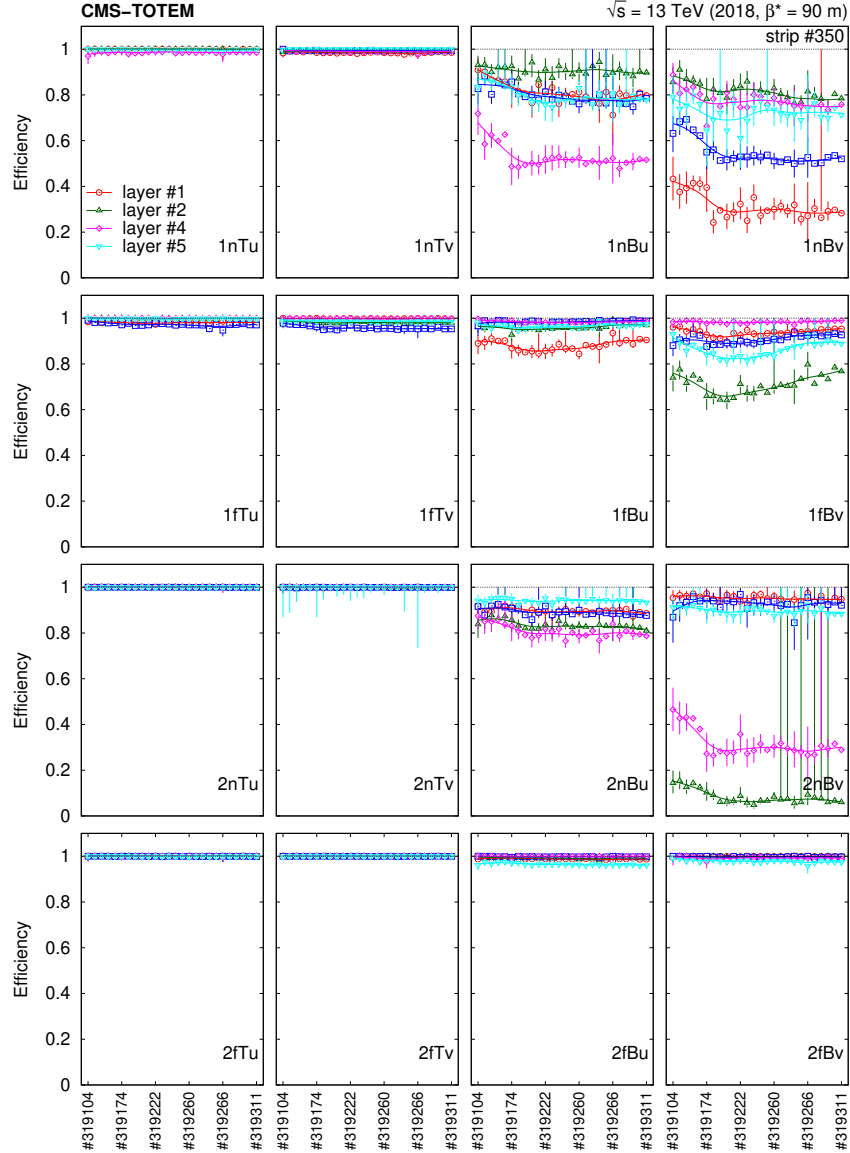


Figure 10. Strip hit efficiencies as functions of the run number for strip #350 in layers 1–5 (coloured points) in various layer groups (labels in the lower right corner). Statistical uncertainties are indicated with vertical bars. Lines are spline interpolations to guide the eye.

3.4 Tracklet efficiencies and joint weights

The tracklet reconstruction efficiencies are determined by means of a simulation based on the strip hit detection efficiencies. Efficiency as a function of the tracklet location at the centre of the RP (the track intercept) and of the track slope is shown for each layer group separately in figure 11, for a representative run. Substantial losses are present at specific tracklet locations and slopes. The periodic efficiency loss seen at every 32nd strip for the far RPs is due to the RP trigger that uses roads of 32 strips to define a track candidate. If the tracklet is in the border region between trigger roads, there is an increased chance that it is lost. This kind of pattern is not observed in the near RPs that were not used in the trigger.

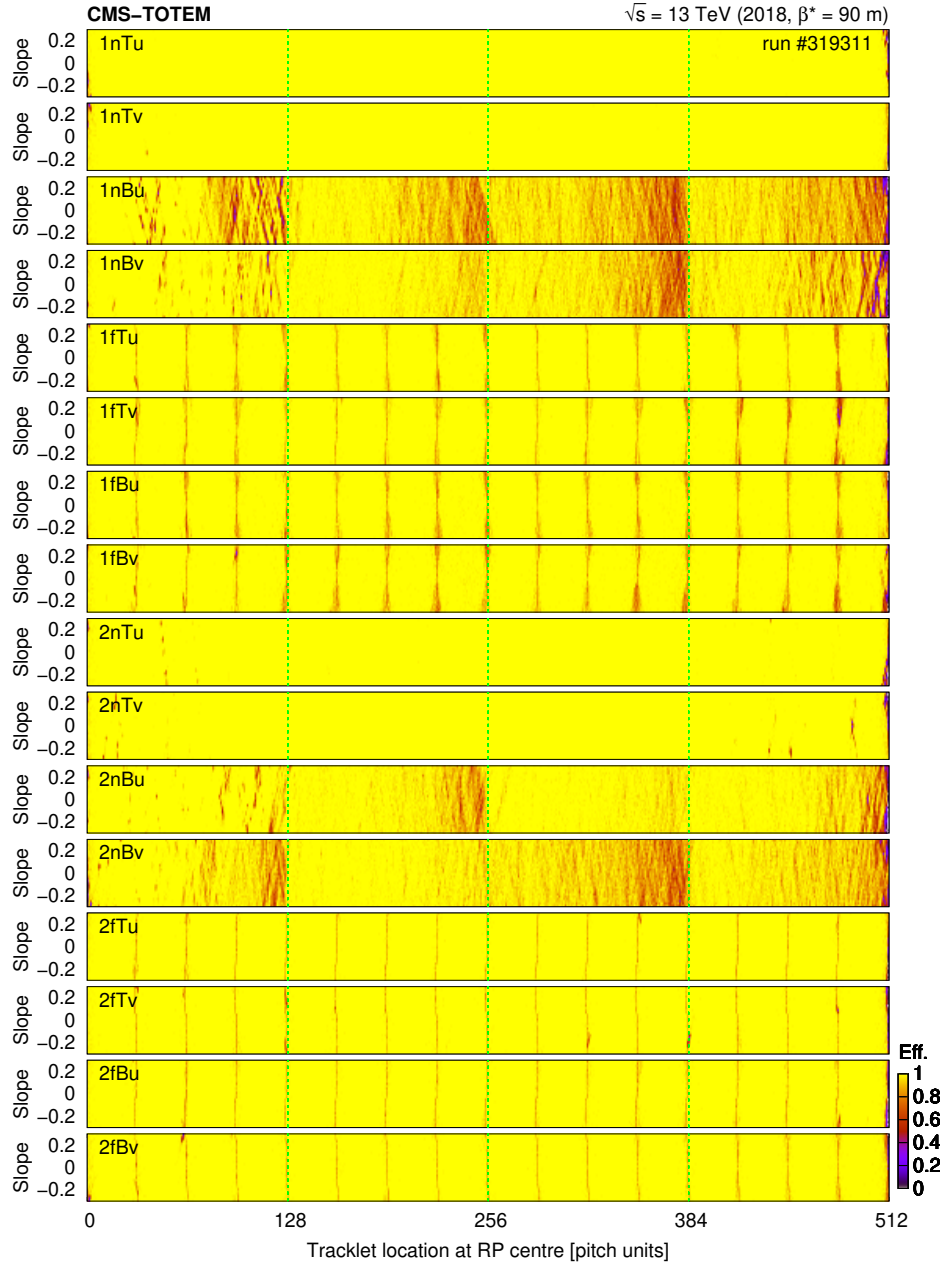


Figure 11. Tracklet reconstruction efficiency (colour scale) as a function of tracklet location at the centre of the RP (intercept) and the track slope, for a representative run, shown for each layer group separately. Yellow regions correspond to fully efficient tracklet reconstruction, whereas the red regions exhibit substantial losses with efficiencies in the range 0.4–0.6. Vertical green lines denote boundaries of the front-end chips.

In a normal event, where both scattered protons are detected by both near and far pots, we have four tracklets, each with u and v projections. The product of their corresponding tracklet efficiencies (obtained from a table, figure 11) gives the probability of detecting such an event. The reciprocal of this joint probability is the joint tracklet weight that is applied in physics analyses. As expected from the low strip hit efficiencies in the bottom RPs, events with trigger configuration BB suffer the most, while the detection of TT events is fully efficient.

Once the tracklet coordinates in u and v directions are fitted, the hit transverse location (x, y) in the global coordinate system, at the centre of the RP (on the “reference surface”), is calculated through a rotation (section 2.2).

The efficiency-corrected distribution of proton hit locations in the x – y plane at the reference surfaces of the eight RPs, are shown in figure 12 for different trigger configurations. The wavy pattern seen in the plots of the events with the diagonal trigger (TB and BT) is a direct consequence of the trigger rejecting a large fraction of elastic events. This is performed by vetoing events where hits in the two arms have similar coordinates but with opposite sign. The halo seen in the 0-track sample for the parallel trigger configurations (TT and BB) shows that those are not elastic events, but overlapping inelastic events where the momentum loss of the scattered protons is significant.

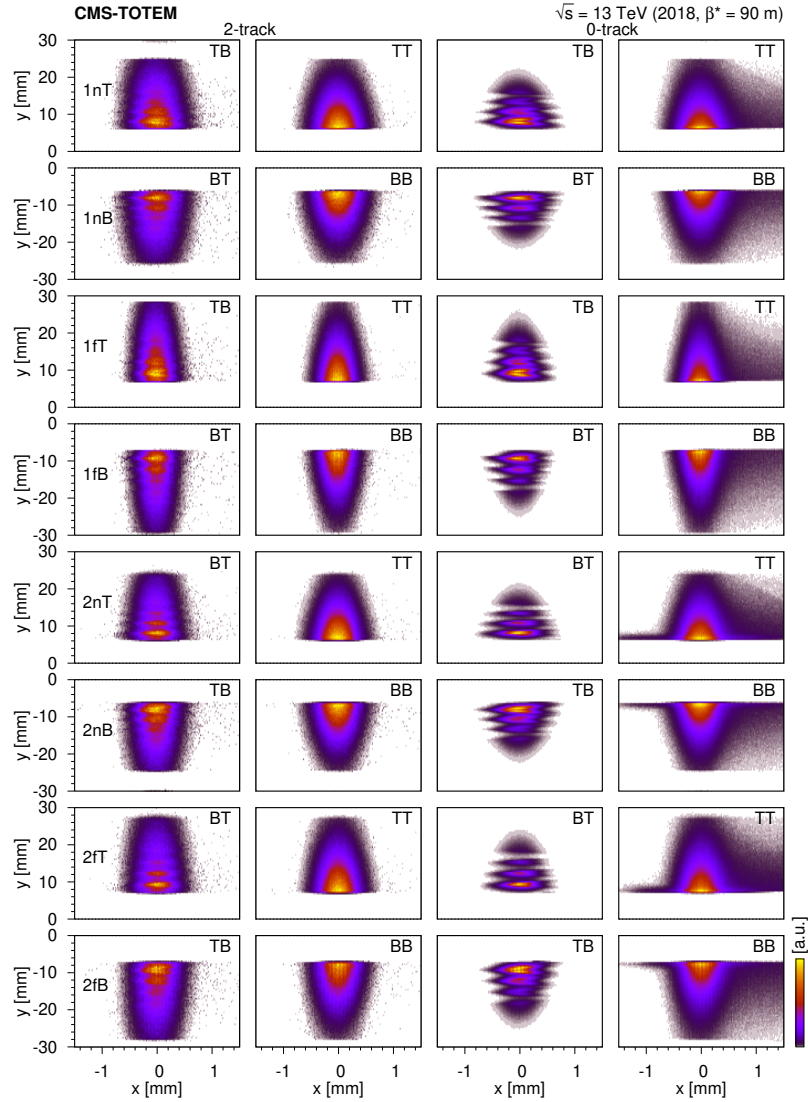


Figure 12. Efficiency-corrected distribution of proton hit locations in the x – y plane at the references surfaces of the eight RPs (rows), for different trigger configurations (labels at the upper right corner). The two columns on the left side refer to the 2-track data set, whereas the two on the right side display distributions based on the 0-track data set. The wavy pattern and the halo seen in the 0-track data set is explained in the text.

4 Proton reconstruction

Our goal is to reconstruct the (p_x, p_y) transverse momentum vectors, or the emission angles (θ_x^*, θ_y^*) , and the locations (x^*, y^*) of the scattered protons in the transverse plane at the nominal IP. This is accomplished by using only the fitted hit locations (x, y) of the proton tracklets at the reference surfaces of the RPs. The deduced local slopes $(dx/dz$ and $dy/dz)$ are not used since those have poor resolution. A detailed cross-check of the beam optics based on the measured hit position covariances, and a precise run-by-run alignment are also described in the following.

4.1 Beam optics

The nominal optics determination and alignment procedure for RPs uses elastic events [19, 20] and MAD-X [21], which is a general purpose accelerator design program. The method exploits kinematical distributions of elastically scattered protons observed in the RPs. It varies the rotation angles and currents of the six quadrupoles between the IP and the RPs for both beams, as well as the beam energy of both beams, each within its uncertainty. Theoretical predictions, as well as Monte Carlo studies, show that the residual uncertainty in the deduced optical parameters is smaller than 0.25%.

The transverse coordinate x of a particle (proton) at position s along the beam line can be described as [22]

$$x(s) = \sqrt{\beta_x(s)\varepsilon} \cos[\phi_0 + \Delta\mu(s)] + D_x(s)\Delta p/p, \quad (4.1)$$

where β is the betatron amplitude, ε is the emittance, ϕ_0 is the phase offset, $\Delta\mu$ is the phase advance, D is the dispersion function, and $\Delta p/p$ is the relative momentum loss of the scattered proton. The quantities characterising the LHC optics are the horizontal and vertical betatron amplitude $\beta(s)$, the magnification $v(s) = \sqrt{\beta(s)/\beta^*} \cos \Delta\mu(s)$, and the effective length $L(s) = \sqrt{\beta(s)\beta^*} \sin \Delta\mu(s)$. The phase advance $\Delta\mu(s)$ is calculated as $\Delta\mu(s) = \int_0^s ds' / \beta(s')$, in other words $d\Delta\mu/ds = 1/\beta(s)$. At the nominal IP ($s = 0$), the location of the particle is $x^* = x(0)$, $y^* = y(0)$, and $\beta^* = \beta(0)$, $\Delta\mu(0) = 0$. The dependences of x on x^* , θ^* , and $\Delta p/p$ around a given location can be linearised, and in an arm for the two RP stations (subscript n for near, and f for far) we have:

$$x_n = v_{x,n}x^* + L_{x,n}\theta_x^* + D_{x,n}\Delta p/p, \quad (4.2)$$

$$x_f = v_{x,f}x^* + L_{x,f}\theta_x^* + D_{x,f}\Delta p/p, \quad (4.3)$$

where the path-dependent dispersion function $D_x(s)$ is needed for the description of particles with momentum spread or momentum loss (Δp). For $\beta^* = 90$ m, the expected values are approximately $L_x \approx 0$, $L_y \approx 262$ m, $v_x \approx -1.9$, $v_y \approx 0.0$, $D_x \approx -0.041$ m, and $D_y \approx 0$, based on table 6.1 in ref. [23]. The actual values are a bit different, asymmetric, and are shown in table 3 (truncated to four or five significant digits), based on MAD-X calculations and subsequent matching with data [19, 20]. The optics is such that the x and the y directions decouple. In the y direction the magnification and dispersion are close to zero; therefore, only the emission angle can be determined with good precision, through a simple proportionality relation $\theta_y^* = y_n/L_{y,n}$ or $y_f/L_{y,f}$.

For elastic and central exclusive collisions ($|\Delta p/p| \ll 1$), the above eqs. (4.2)–(4.3) can be solved as

$$x^* = (L_{x,f}x_n - L_{x,n}x_f)/d, \quad (4.4)$$

$$\theta_x^* = (v_{x,n}x_f - v_{x,f}x_n)/d, \quad (4.5)$$

Table 3. Nominal values of beam optics variables (magnifications v , effective lengths L) [19, 20], truncated to four or five significant digits.

Arm	Station	v_x	L_x [m]	v_y	L_y [m]
1	near	-2.204	3.1042	0.032395	238.2
1	far	-1.884	-0.5225	0.007509	271.3
2	near	-2.245	0.1943	0.018513	238.3
2	far	-1.923	-2.9508	-0.008295	271.3

where the determinant is $d \equiv v_{x,n}L_{x,f} - v_{x,f}L_{x,n}$. It can be shown that d equals the distance between the two RP stations, more precisely the distance between their reference surfaces in the beam direction (in our case, $d = 7000$ mm).

Cross-checks of beam optics were performed with data, based on the measured variances and covariance of the proton hit positions in x . Once these quantities are measured, the variance $\text{var}(x^*)$ is obtained as

$$\text{var}(x^*) = \frac{\text{var}(x_n) \text{var}(x_f) - \text{cov}(x_n, x_f)^2}{\text{var}(x_f)v_{x,n}^2 - 2 \text{cov}(x_n, x_f)v_{x,n}v_{x,f} + \text{var}(x_n)v_{x,f}^2}, \quad (4.6)$$

which does not depend on the actual values of the effective lengths, but only on the given magnifications $v_{x,n}$ and $v_{x,f}$, and the measured hit position variances and covariances. The ratio of far and near effective lengths is

$$\frac{L_{x,f}}{L_{x,n}} = \sqrt{\frac{\text{var}(x_f) - \text{var}(x^*)v_{x,f}^2}{\text{var}(x_n) - \text{var}(x^*)v_{x,n}^2}}. \quad (4.7)$$

The variance of the emission angle is

$$\text{var}(\theta_x^*) = \frac{\text{var}(v_{x,f}x_n - v_{x,n}x_f)}{|d|^2}. \quad (4.8)$$

With that, the effective lengths are

$$L_{x,n} = \sqrt{\frac{\text{var}(x_n) - \text{var}(x^*)v_{x,n}^2}{\text{var}(\theta_x^*)}}, \quad L_{x,f} = \sqrt{\frac{\text{var}(x_f) - \text{var}(x^*)v_{x,f}^2}{\text{var}(\theta_x^*)}}. \quad (4.9)$$

The estimated size of the beam spot in the x direction is $\sigma_{x^*} \approx 100 \mu\text{m}$, consistent with measurements using charged particles reconstructed in the central CMS silicon tracker. The emission angle is $\sigma_{\theta_x^*} \approx 28 \mu\text{rad}$ for 0-track and $42 \mu\text{rad}$ for 2-track events. These values are substantially larger than the beam divergence ($2.1 \mu\text{rad}$, section 2.1), since the characteristic width of the proton emission angle is dominated by the much larger scale of the various physics processes. The ratio of effective lengths for Arm 1 is $L_{x,f}/L_{x,n} \approx -0.3$, and for Arm 2 $L_{x,f}/L_{x,n} \approx -4$. These are to be compared with the nominal values -0.17 and -15 , yielding only a poor agreement. This first look is refined, and shows a much better agreement, once the precise run-by-run RP alignment is put in place (section 4.3).

4.2 Effects of the IP transverse location and proton emission angle

The correlation of the proton hit locations in the x and y directions reflects various physics effects, such as momentum loss, width of the beam at the nominal IP, and the influence of effective length ratios.

For elastic collisions, the momentum loss of the protons is very small, its spread is $|\Delta p/p| \lesssim 10^{-4}$, reflecting the momentum variance of the beam. This corresponds to about $5 \mu\text{m}$ hit position spreading, which is hardly detectable. The acceptance of the central tracker limits the detectable 2-track central exclusive events to $|\Delta p/p| \lesssim 10^{-3}$ through momentum conservation, corresponding to a $50 \mu\text{m}$ shift in hit position (comparable to the strip width of $66 \mu\text{m}$). Here “shift” refers to the difference between the true hit position and the predicted track impact point position assuming the nominal beam momentum. For diffractive and highly inelastic collisions, where the momentum loss of the incoming protons is sizeable, a well-detectable displacement is visible: a 10% momentum loss corresponds to a 5 mm shift. The events show a linear correlation between x_f and x_n (figure 13) with a slope $D_{x,f}/D_{x,n} \approx 0.68$ for Arm 1, and ≈ 0.64 for Arm 2, as expected.

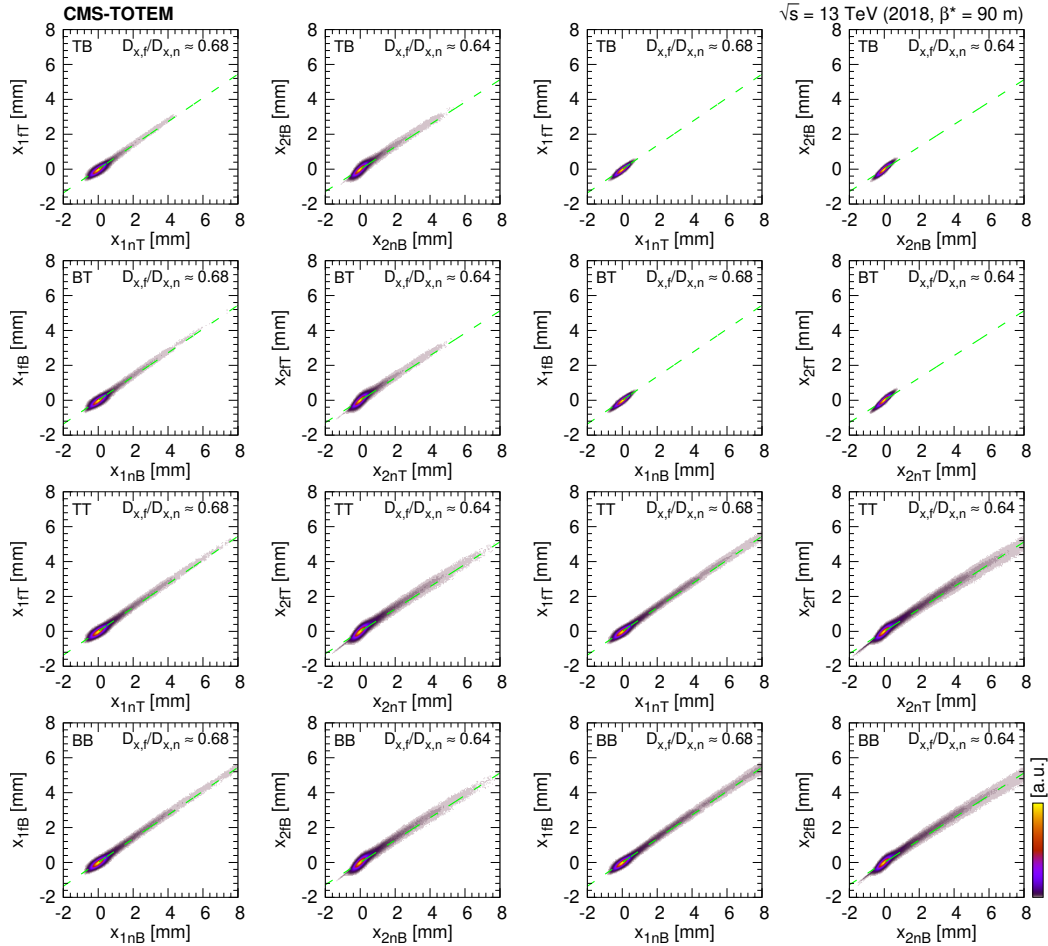


Figure 13. Correlation of proton hit locations in the x direction (two-dimensional occupancy histograms) in the far and near RPs, shown for various trigger configurations (TB, BT, TT, and BB, in rows). The two columns on the left side refer to the 2-track data set, and the two on the right side display distributions based on the 0-track data set. A straight line corresponding to the expectation $x_f = x_n D_{x,f}/D_{x,n}$ is also plotted, where $D_{x,f}/D_{x,n} \approx 0.68$ for Arm 1, and ≈ 0.64 for Arm 2. The plots are produced with the final detector alignment.

The effect of the beam width at the nominal IP, $\sigma_{x,y}^* \sim O(100 \mu\text{m})$, can be propagated to the RPs ($v_x x^*$) and results in a spread of about $200 \mu\text{m}$. Such an event-by-event shift is correlated between the two arms (the protons come from the same actual IP) and is well detectable. For a transverse momentum $p_x = 200 \text{ MeV}$ we have $\theta_x^* \approx 10^{-4}$, which results in a shift of $20\text{--}300 \mu\text{m}$. The higher values are already detectable and in the case of elastic collisions there should be a clear correlation between the two arms.

In the case of small x values (figure 14), the distribution consists mostly of elastic and central exclusive events with $\Delta p/p \approx 0$. For the diagonal configuration, the 0-track data set (mostly elastic events) shows a slope of 0.79 for Arm 1, and 0.92 for Arm 2. For the parallel configuration (in part central exclusive events), the slope is 0.70–0.73 for Arm 1, and 0.95–0.99 for Arm 2. The slopes for elastic and central exclusive events differ because the variance of the proton emission angle $\text{var}(\theta_x^*)$ in the two cases is different. The quantities shown in figure 14 are used for estimating $\text{var}(x^*)$ using eq. (4.6).

In the y direction, the measured data match our expectations with the slope $L_{y,f}/L_{y,n} = 271.3/238.2 \approx 1.14$ (figure 15).

4.3 Absolute run-by-run alignment

An inspection of collision events shows apparent deviations from momentum conservation. This is corrected by means of additional shifts of the RPs in the x and y directions. This absolute alignment is tested through symmetry and momentum conservation by studying the distributions of the deduced IP coordinates and of the momentum sum, and more specifically their means.

The alignment in both the x and y directions must be performed for each run separately, since sizeable apparent displacements from run to run are observed. The changes are mostly due to the drifting LHC proton orbit, since the RP movement system ensures a position reproducibility of about $20 \mu\text{m}$. However, instead of correcting the incoming proton direction, for the sake of simplicity, in the present analysis the RPs are artificially shifted. The goal is to determine the additional shifts δx and δy for the eight RPs, i.e., altogether 16 values.

The measured deviations $\vec{\Delta}$ and the local shifts $\vec{x}_0$ are connected through a linear transformation $A\vec{x}_0 = \vec{\Delta}$, where A is a matrix. The shifts $\vec{\delta x}$ are such that $A(\vec{x}_0 + \vec{\delta x}) = 0$, and therefore they can be determined from solving $A\vec{\delta x} = -\vec{\Delta}$.

The alignment in the x direction is based on the nearly Gaussian hit location and momentum sum distributions, since they must be symmetric about zero:

- the location of the primary interaction $x^* = (x_n L_{x,f} - x_f L_{x,n})/d$. This quantity is calculated in a single arm (1 or 2), using either the top or the bottom pots (T or B), hence the notations 1T, 1B, 2T, and 2B.
- the sum of particle momenta $\sum p_x$ in elastic or exclusive events. For scattered protons in the RPs, p_x is calculated as $p_x = p_{\text{beam}}(x_f v_{x,n} - x_n v_{x,f})/d$.

We can use the measured means of 16 distributions: the location of the IPs x^* , calculated from RP arm configurations 1T, 1B, 2T, and 2B (4 values); the sum of the proton transverse momenta $\sum p_x$ for RP trigger configurations TB, BT, TT, and BB (4 values); the local hit positions x in each

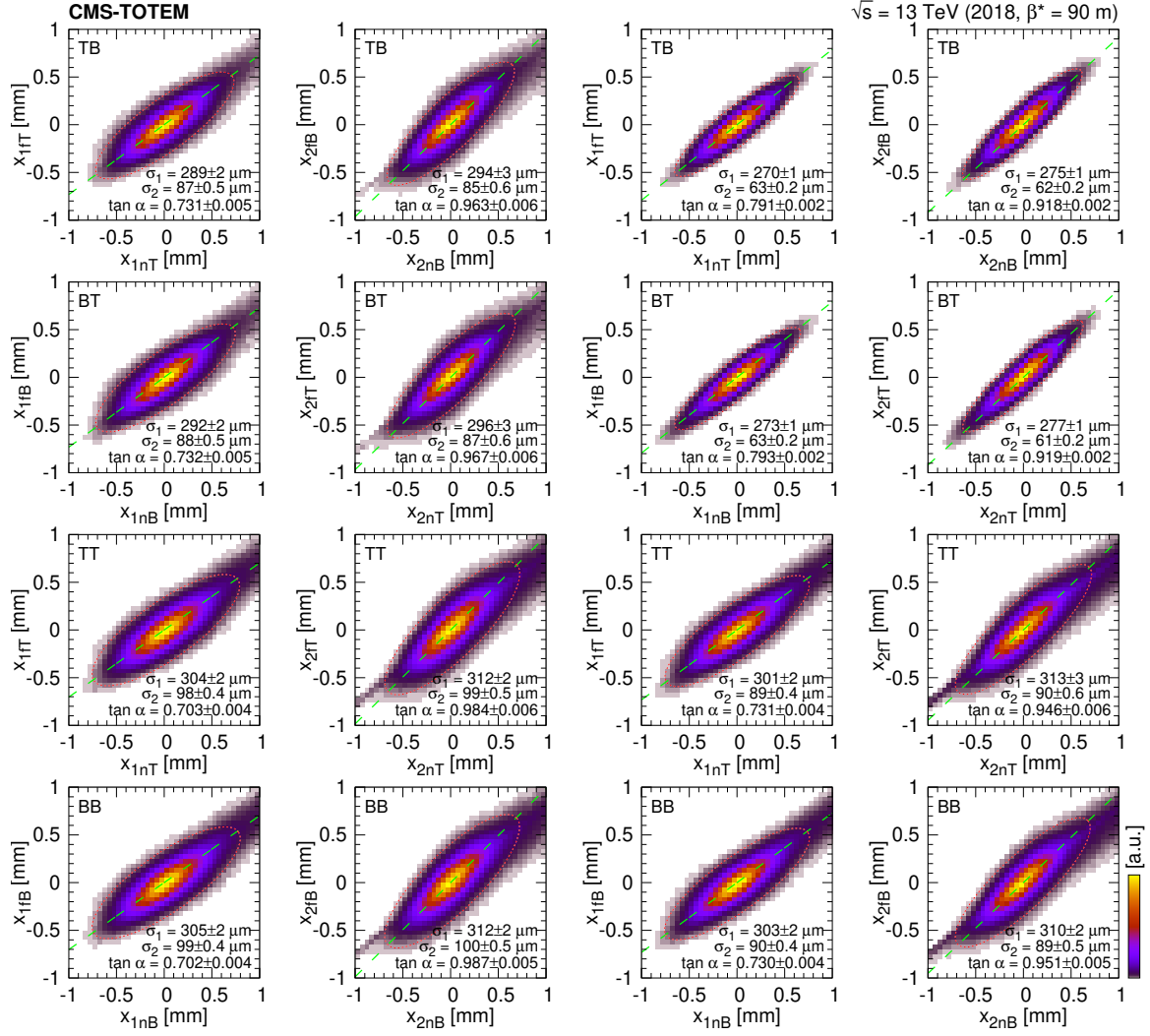


Figure 14. Correlation of proton hit locations in the x direction (two-dimensional occupancy histograms) in the far and near RPs, shown for various trigger configurations (TB, BT, TT, and BB, in rows), with a restricted scale. Parameters (standard deviations in major and minor axis directions σ_1 and σ_2 , and the rotation angle α) of the fitted tilted two-dimensional normal distributions are displayed in the plots. The corresponding ellipses cover 99% of the points; the dashed green lines indicate their major axes. The two columns on the left side refer to the 2-track data set, whereas the two on the right side display distributions based on the 0-track data set. The plots are produced with the final detector alignment.

RP (8 values). The transformation matrix is

$$A_x = \begin{pmatrix} L_{1f}/d & -L_{1n}/d & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & L_{1f}/d & -L_{1n}/d & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & L_{2f}/d & -L_{2n}/d & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & L_{2f}/d & -L_{2n}/d \\ -pv_{1f}/d & pv_{1n}/d & 0 & 0 & 0 & 0 & -pv_{2f}/d & pv_{2n}/d \\ 0 & 0 & -pv_{1f}/d & pv_{1n}/d & -pv_{2f}/d & pv_{2n}/d & 0 & 0 \\ -pv_{1f}/d & pv_{1n}/d & 0 & 0 & -pv_{2f}/d & pv_{2n}/d & 0 & 0 \\ 0 & 0 & -pv_{1f}/d & pv_{1n}/d & 0 & 0 & -pv_{2f}/d & pv_{2n}/d \end{pmatrix}, \quad (4.10)$$

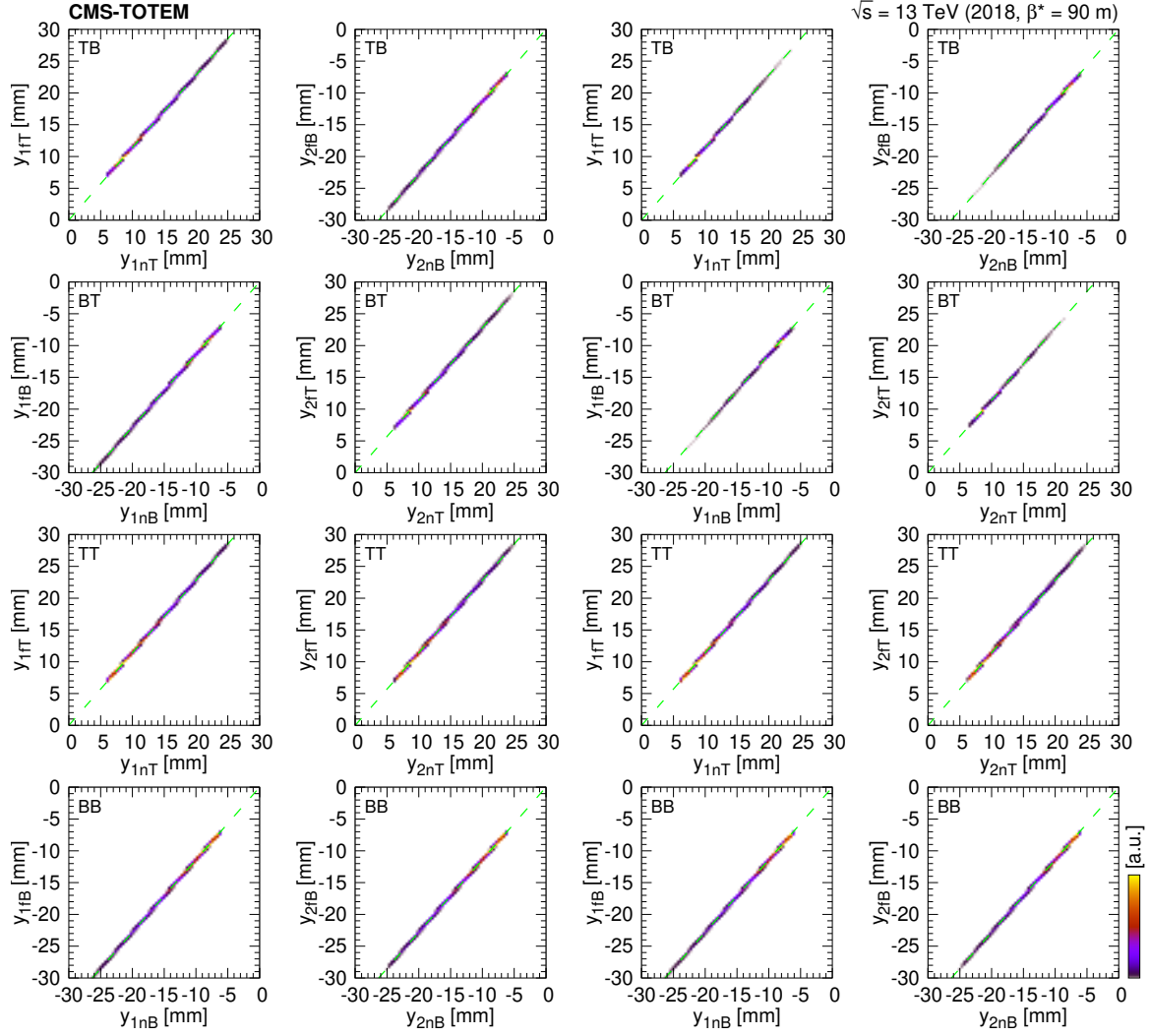


Figure 15. Correlation of proton hit locations in the y direction (two-dimensional occupancy histograms) in the far and near RPs, shown for various trigger configurations (TB, BT, TT, and BB, in rows). The two columns on the left side refer to the 2-track data set, whereas the two on the right side display distributions based on the 0-track data set. A straight line corresponding to the expectation $y_f = y_n L_{y,f}/L_{y,n}$ is also plotted, where $L_{y,f}/L_{y,n} \approx 1.14$. The plots are produced with the final detector alignment. The apparent piecewise linear segments are simply the consequence of the binning.

where $p = p_{\text{beam}}$, and the transformation itself is

$$A_x \begin{pmatrix} \delta x_{1nT} \\ \delta x_{1fT} \\ \delta x_{1nB} \\ \delta x_{1fB} \\ \delta x_{2nT} \\ \delta x_{2fT} \\ \delta x_{2nB} \\ \delta x_{2fB} \end{pmatrix} = \begin{pmatrix} -\langle x_{1T}^* \rangle \\ -\langle x_{1B}^* \rangle \\ -\langle x_{2T}^* \rangle \\ -\langle x_{2B}^* \rangle \\ -\langle \sum p_{x,TB} \rangle \\ -\langle \sum p_{x,BT} \rangle \\ -\langle \sum p_{x,TT} \rangle \\ -\langle \sum p_{x,BB} \rangle \end{pmatrix}. \quad (4.11)$$

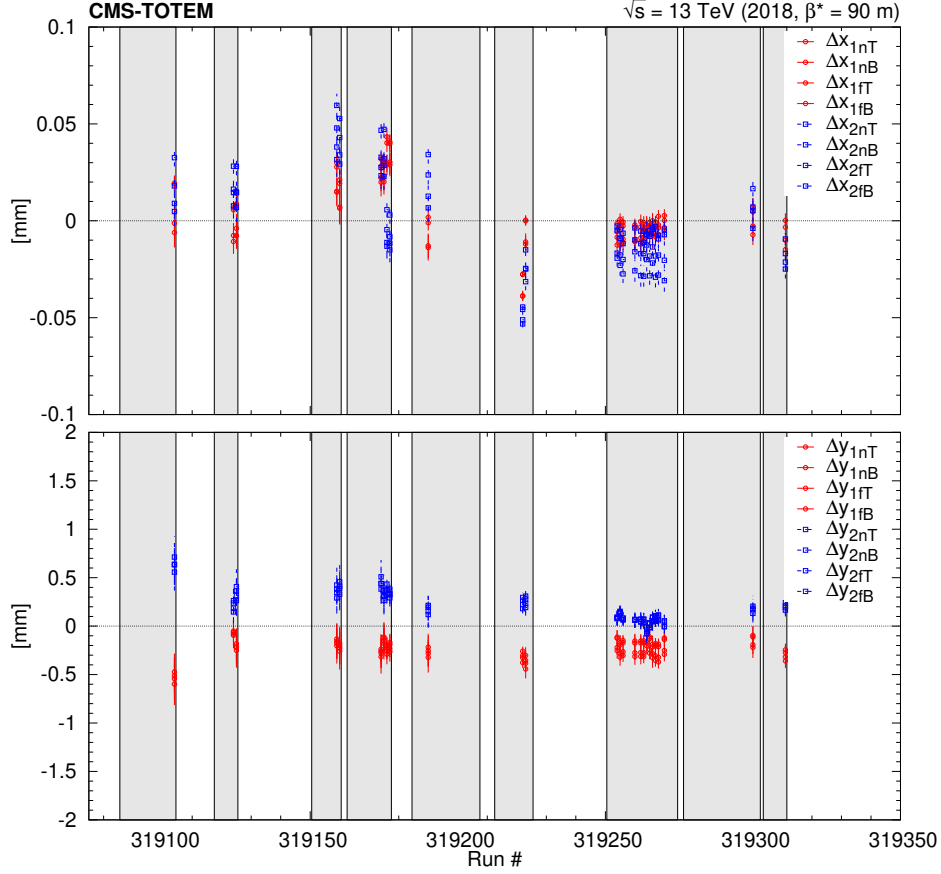


Figure 16. Deduced displacements of RPs in the x (top) and y (bottom) directions as a function of run number. Statistical uncertainties are shown with vertical bars. The LHC fills are indicated by grey areas.

The top and bottom RPs are independently movable, and their hit location distribution in the y direction has a gap in the middle. In addition, because of the varying p_y acceptance of various pots, the normalisation of the distributions in the top and bottom parts is unrelated. Hence the alignment in the y direction cannot be based on the hit location distributions alone. There are two variables whose distributions must be symmetric about zero, and are not biased:

- the location of the primary interaction y^* . In an arm, using either the top or the bottom RPs, it is calculated as $y^* = (y_n L_{y,f} - y_f L_{y,n})/d$. There are four such independent equations (two arms, top or bottom RPs).
- the sum of particle momenta $\sum p_y$ in elastic or exclusive events. For scattered protons in the RPs, p_y is calculated as $p_y = p_{\text{beam}}[2(y_n/L_{y,n} + y_f/L_{y,f})]$. There are four such independent equations, one for each configuration.

We have the measured means of twelve distributions: the location of the IPs y^* , calculated from RP pairs 1T, 1B, 2T, and 2B (4 values); the sum of proton transverse momenta $\sum p_y$ for RP trigger configurations TB, BT, TT, and BB (4 values); the averaged local hit positions y in RP groups 1n,

1f, 2n, and 2f (4 values). The transformation matrix is

$$A_y = \begin{pmatrix} L_{1f}/d & -L_{1n}/d & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & L_{1f}/d & -L_{1n}/d & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & L_{2f}/d & -L_{2n}/d & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & L_{2f}/d & -L_{2n}/d \\ p/(2L_{1n}) & p/(2L_{1f}) & 0 & 0 & 0 & 0 & p/(2L_{2n}) & p/(2L_{2f}) \\ 0 & 0 & p/(2L_{1n}) & p/(2L_{1f}) & p/(2L_{2n}) & p/(2L_{2f}) & 0 & 0 \\ p/(2L_{1n}) & p/(2L_{1f}) & & & p/(2L_{2n}) & p/(2L_{2f}) & 0 & 0 \\ 0 & 0 & p/(2L_{1n}) & p/(2L_{1f}) & 0 & 0 & p/(2L_{2n}) & p/(2L_{2f}) \end{pmatrix}, \quad (4.12)$$

and the transformation itself is

$$A_y \begin{pmatrix} \delta y_{1nT} \\ \delta y_{1fT} \\ \delta y_{1nB} \\ \delta y_{1fB} \\ \delta y_{2nT} \\ \delta y_{2fT} \\ \delta y_{2nB} \\ \delta y_{2fB} \end{pmatrix} = \begin{pmatrix} -\langle y_{1T}^* \rangle \\ -\langle y_{1B}^* \rangle \\ -\langle y_{2T}^* \rangle \\ -\langle y_{2B}^* \rangle \\ -\langle \sum p_{y,TB} \rangle \\ -\langle \sum p_{y,BT} \rangle \\ -\langle \sum p_{y,TT} \rangle \\ -\langle \sum p_{y,BB} \rangle \end{pmatrix}. \quad (4.13)$$

The optimisation of the additional shifts was performed through a joint least squares fit using the estimated variances of $\langle x^* \rangle$ and $\langle y^* \rangle$ values, and those of the momentum sums. The extracted values in the x and y directions as a function of run number are shown in figure 16. All RPs in an arm need to be artificially shifted in a coordinated manner, although the two arms appear to be independent. The necessary run-by-run adjustments are in the range $\pm 50 \mu\text{m}$ in x , and $\pm 0.5 \text{ mm}$ in y . The time dependence of the additional shifts was examined, but they show no obvious periodic behaviour. We conclude that the observed behaviour does not reflect an actual displacement of the RPs, but the drifting of the incoming proton beam orbits. The difference between the x and y directions is the consequence of the special LHC beam optics configuration at the location of the RPs (section 4.1). The effective length in the x direction is close to zero ($L_x \approx 0$), hence the horizontal position of the proton in the RP principally depends on the IP coordinate x^* . The magnification in the y direction is close to zero ($v_y \approx 0$) which makes the vertical position of the proton in the RP mainly dependent on the scattering angle θ_y^* and not the IP coordinate y^* . Hence any beam-related effect plays out rather differently in the two directions.

Details and cross-checks for a specific run (#319311) after full alignment are shown in figure 17, including the distribution of the IP coordinates (x^* , y^*) and that of the four-particle momentum sum ($\sum p_x$, $\sum p_y$) for each RP configuration, as well as the distribution of the local hit coordinates in the x (single Gaussian) and y directions (separate Gaussians). The measured residuals and those expected from the extracted displacements are shown in figure 18. Although not all the constraints can be satisfied at the same time, the relevant quantities used for event selection and physics analysis, i.e., the momentum sums $\sum p_x$ and $\sum p_y$, are well optimised.

Estimates, based on measured data, of the effective lengths at the location of the near ($L_{n,x}$) and far pots ($L_{f,x}$) as functions of the run number are shown in figure 19. They were deduced from

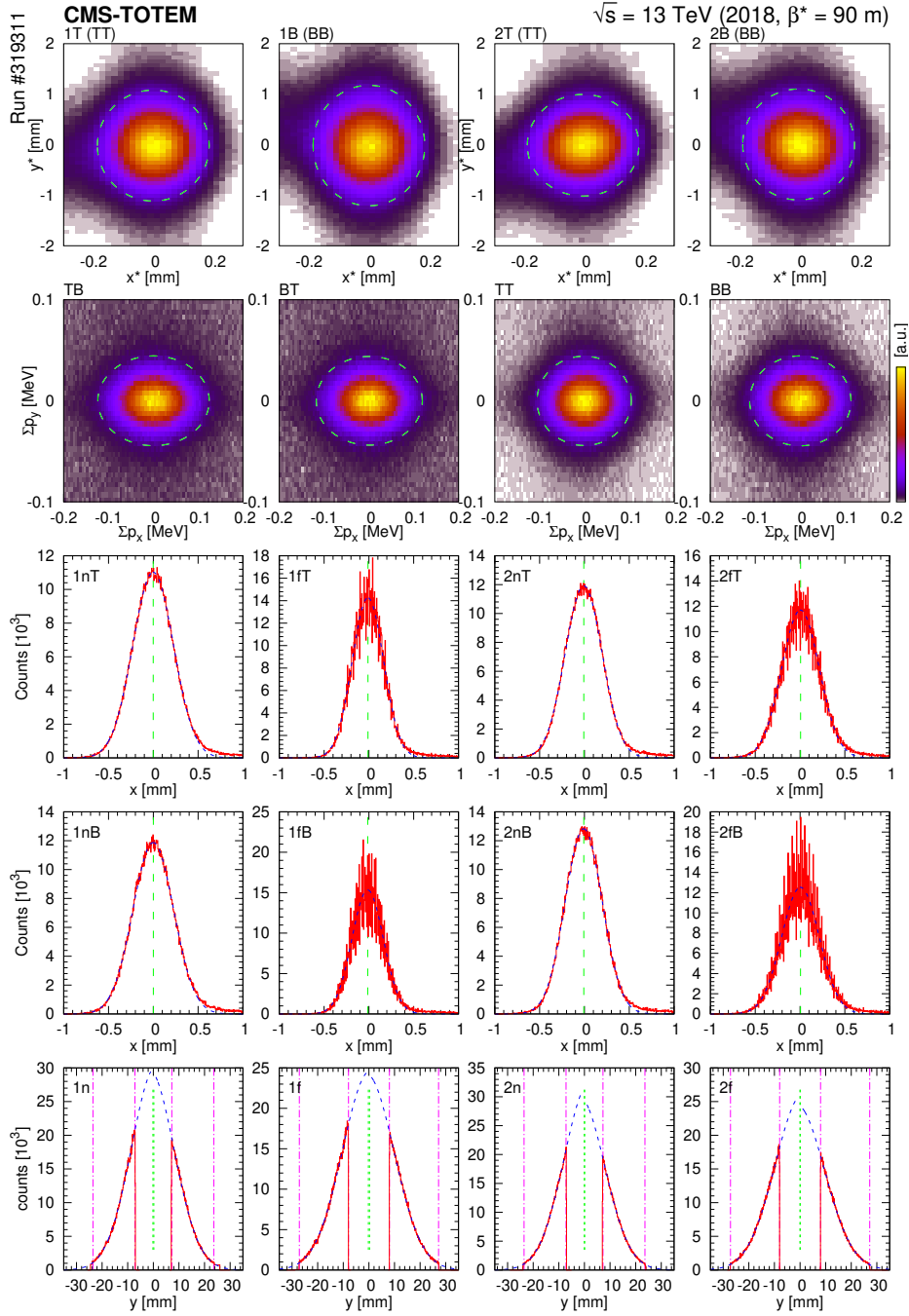


Figure 17. Cross-check of the full alignment, shown here for run #319311. From top to bottom: Distribution of the IP coordinates (x^* , y^*) for RP arm configurations 1T, 1B, 2T, and 2B. Distribution of the four-particle momentum sum (Σp_x , Σp_y) for the RP trigger configurations TB, BT, TT, and BB. In both cases the two-dimensional Gaussian fits are indicated (at 2σ) with green dotted ellipses. Distribution of local hits in the RPs in the x (single Gaussian) and y directions (separate Gaussians). Dashed blue curves represent the Gaussian fits, vertical green dashed lines indicate the deduced relative shifts, vertical magenta dash-dotted lines on y plots show fit ranges.

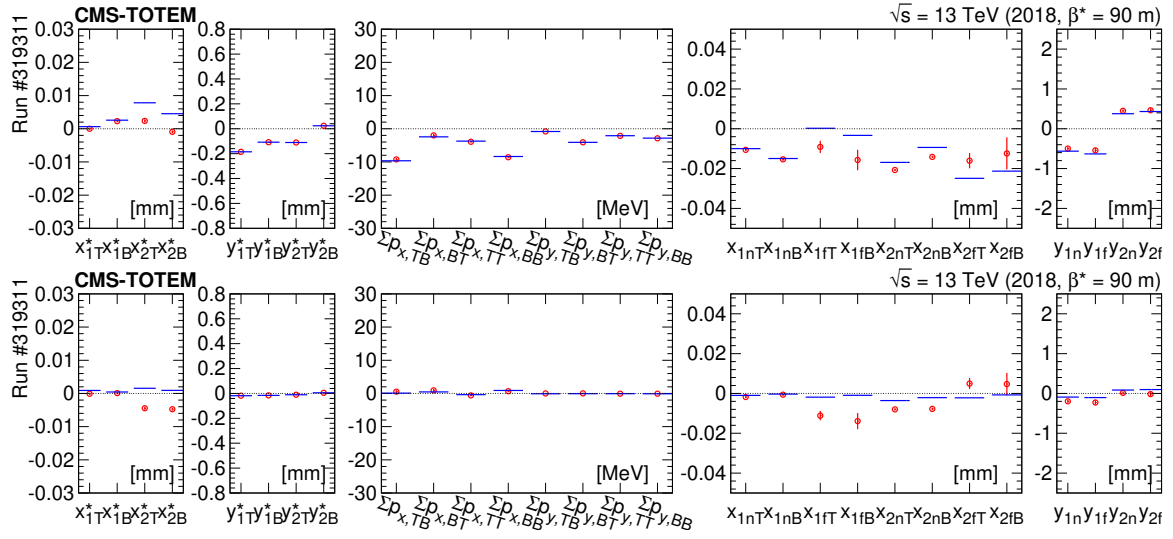


Figure 18. The measured residuals (red symbols) and those expected from the extracted displacements (horizontal blue lines) for run #319311, before (upper) and after (lower) the alignment.

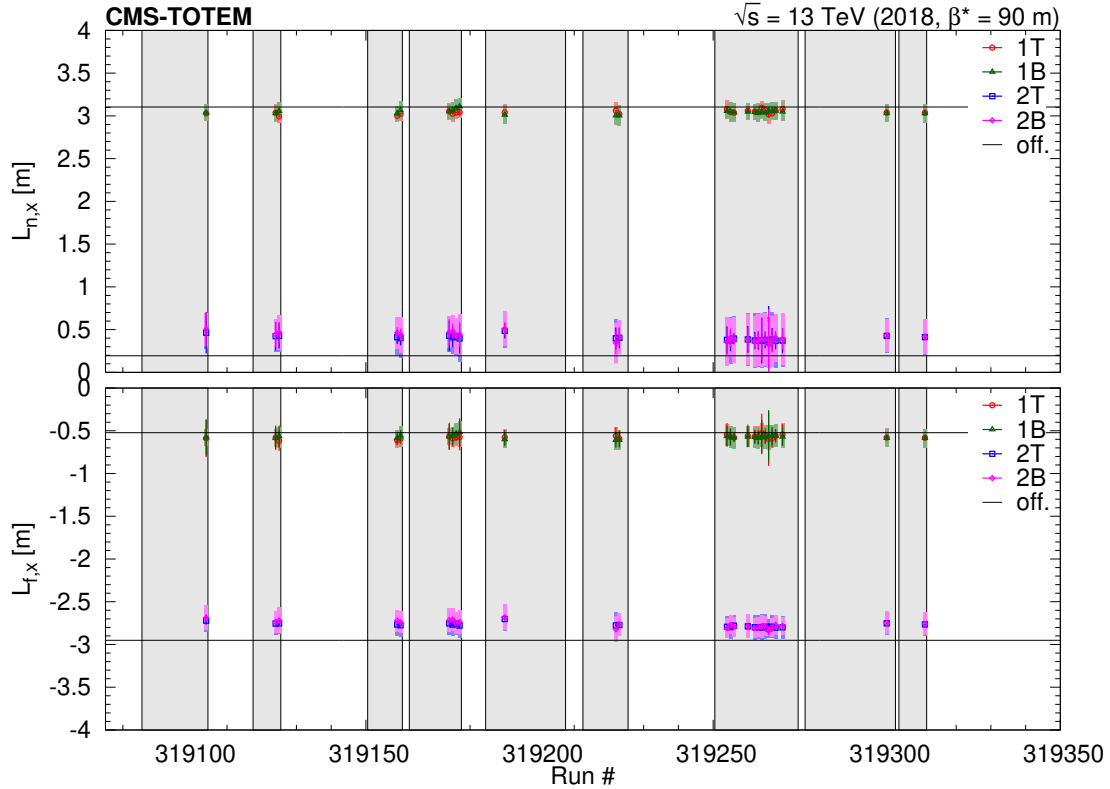


Figure 19. Effective lengths at the location of the near ($L_{n,x}$) and far pots ($L_{f,x}$) as functions of the run number, deduced from near-far hit covariances in RPs for RP arm configurations 1T, 1B, 2T, and 2B. Statistical uncertainties are indicated with error bars, systematic ones are plotted with shaded rectangles. Values of the nominal TOTEM optics parameters (table 4) are also shown with horizontal black lines. LHC fills are indicated by grey areas.

near-far hit covariances in RPs for arm configurations 1T, 1B, 2T, and 2B. Systematic uncertainties are obtained by varying the size of the selection ellipse (figure 14) by 50%, and by varying the values of magnification ($v_{x,n}$ and $v_{x,f}$) within their expected uncertainties (0.2%). Values of the nominal optics [19, 20] are also plotted for reference, with black lines. The comparison between the nominal and averaged estimates from collected events is given in table 4 where any run-by-run variation of the estimated value is included in the uncertainty. They are in good agreement.

Table 4. Nominal values and estimates of the effective lengths L_x , truncated to two decimal places. For the estimates, the systematic uncertainties are indicated; the statistical ones are negligible.

Arm	Station	L_x [m]	
		Nominal	Estimated
1	near	3.10	3.05 ± 0.11
1	far	-0.52	-0.57 ± 0.12
2	near	0.19	0.39 ± 0.16
2	far	-2.95	-2.78 ± 0.12

4.4 Results

The locations of the primary pp interactions in the x^*-y^* plane at the IP using RPs in Arm 1 or in Arm 2 are shown for each trigger configuration in figure 20. All the distributions are well centred at (0,0). The elongated regions at negative x^* values correspond to protons with large momentum loss. The width of the distributions is the result of various factors: the beam spot size, the effect of multiple scattering of the protons within the RP material, and the local position resolution of the RPs. The joint distributions of x^* (or y^*) coordinates deduced using RPs in Arm 1 and 2 are shown for each trigger configuration in figure 21. The x^* coordinates are determined with good precision, and they correlate well between Arm 1 and 2, with a beam spot size of $135/\sqrt{2} \approx 95 \mu\text{m}$ and resolution $10/\sqrt{2} \approx 6\text{--}7 \mu\text{m}$. The y^* coordinates have much larger uncertainties, but their distributions are well centred around (0,0), with tails from non-exclusive events.

The standard deviation of the momentum sum $\sum p_x$ for the 0-track data as a function of the predicted standard deviation from the RP position resolution is shown in figure 22, where the result of a fit using the functional form $(\sigma_0^2 + \sigma_{\sum p_x}^2)^{1/2}$ is indicated. The constant contribution of $\sigma_0 \approx 39 \text{ MeV}$ is the result of several factors: the divergence of both incoming proton beams ($\Delta\sigma_0 \approx 20 \text{ MeV}$, section 2.1), multiple scattering of the protons within the RP material, and most importantly the physics process itself. Here inelastic scattering contributes significantly to σ_0 if undetected particles lead to an apparent momentum imbalance.

Distributions of the sum of the scattered proton momenta ($\sum_2 p_x, \sum_2 p_y$), two particles, for diagonally triggered events are shown in figure 23, left. The measured distributions in the $\sum_2 p_y$ direction are slightly distorted, a consequence of the elastic veto (section 3.4). Distributions of the sum of scattered proton and central hadron momenta ($\sum_4 p_x, \sum_4 p_y$), four particles, shown for each trigger configuration for 2-track events, are plotted in figure 23, right. Both distributions are well centred on (0,0).

The distribution of the sum of scattered proton and central hadron momenta and the sum of scattered proton momenta ($\sum_4 p_x$ and $\sum_2 p_x, \sum_4 p_y$ and $\sum_2 p_y$) is shown for each trigger configuration

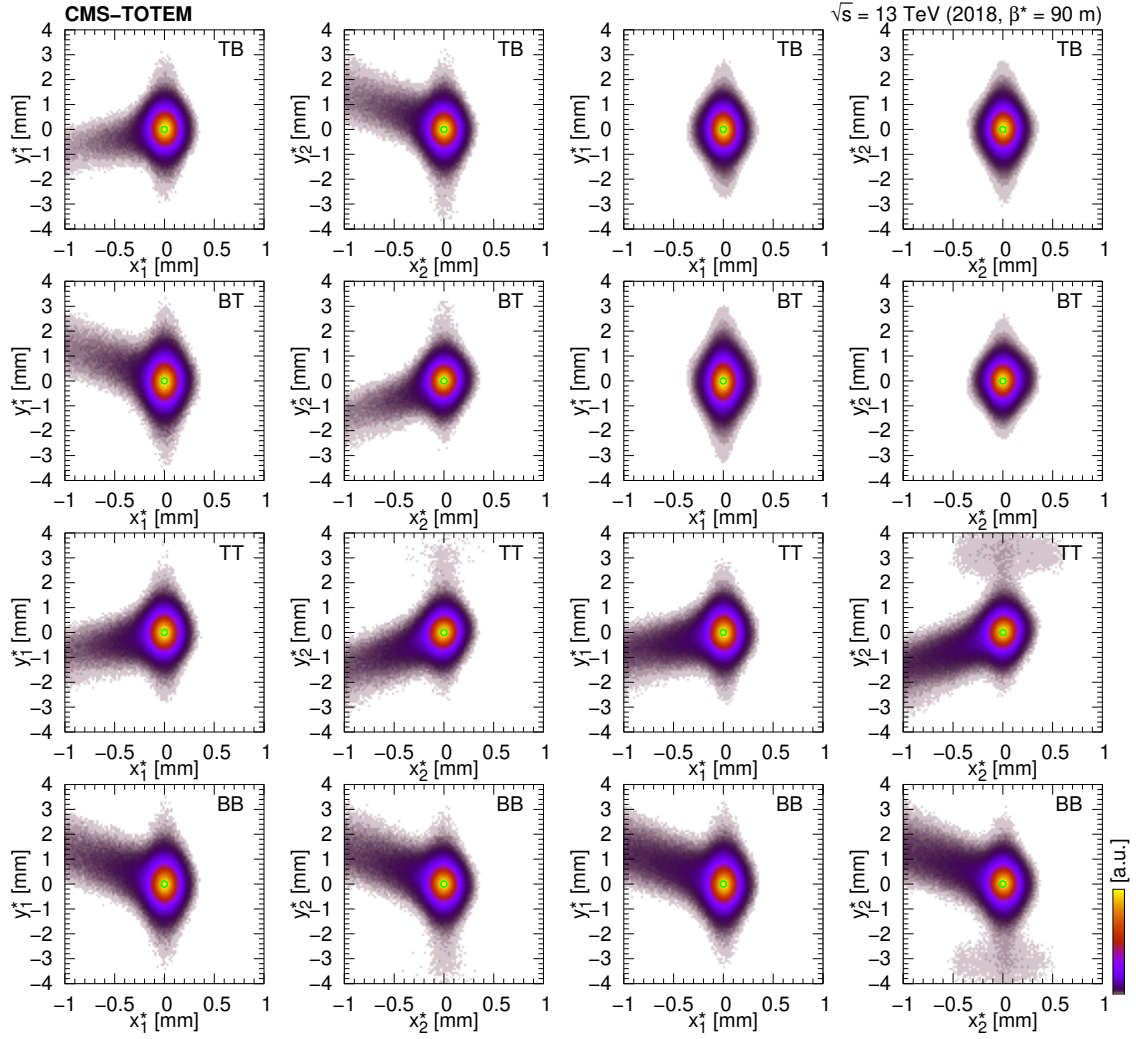


Figure 20. Location of the primary pp interaction in the x^*-y^* plane at the IP using RPs in Arm 1 or 2 (subscripts 1 or 2), shown for various trigger configurations (TB, BT, TT, and BB, in rows). The two columns on the left side refer to the 2-track data set, whereas the two on the right side display distributions based on the 0-track data set. The elongated regions at negative x^* values correspond to events with large proton momentum loss. The green circles mark (0, 0).

for 2-track events in figure 24. The contributions of true elastic (only two scattered protons, vertical band) and true central exclusive (two scattered protons and two central charged hadrons, horizontal band) are well visible. In addition, a slanted area due to non-exclusive or inelastic background is present.

The procedures just described are used for the precise transverse momentum measurement of the scattered protons, for event classification and selection in the physics analysis of central exclusive production, where two oppositely charged hadrons are detected by the CMS silicon tracker [3].

5 Summary

The Roman pot detectors of the TOTEM experiment are used to reconstruct the transverse momentum of scattered protons and to estimate the transverse location of the primary interaction. In this

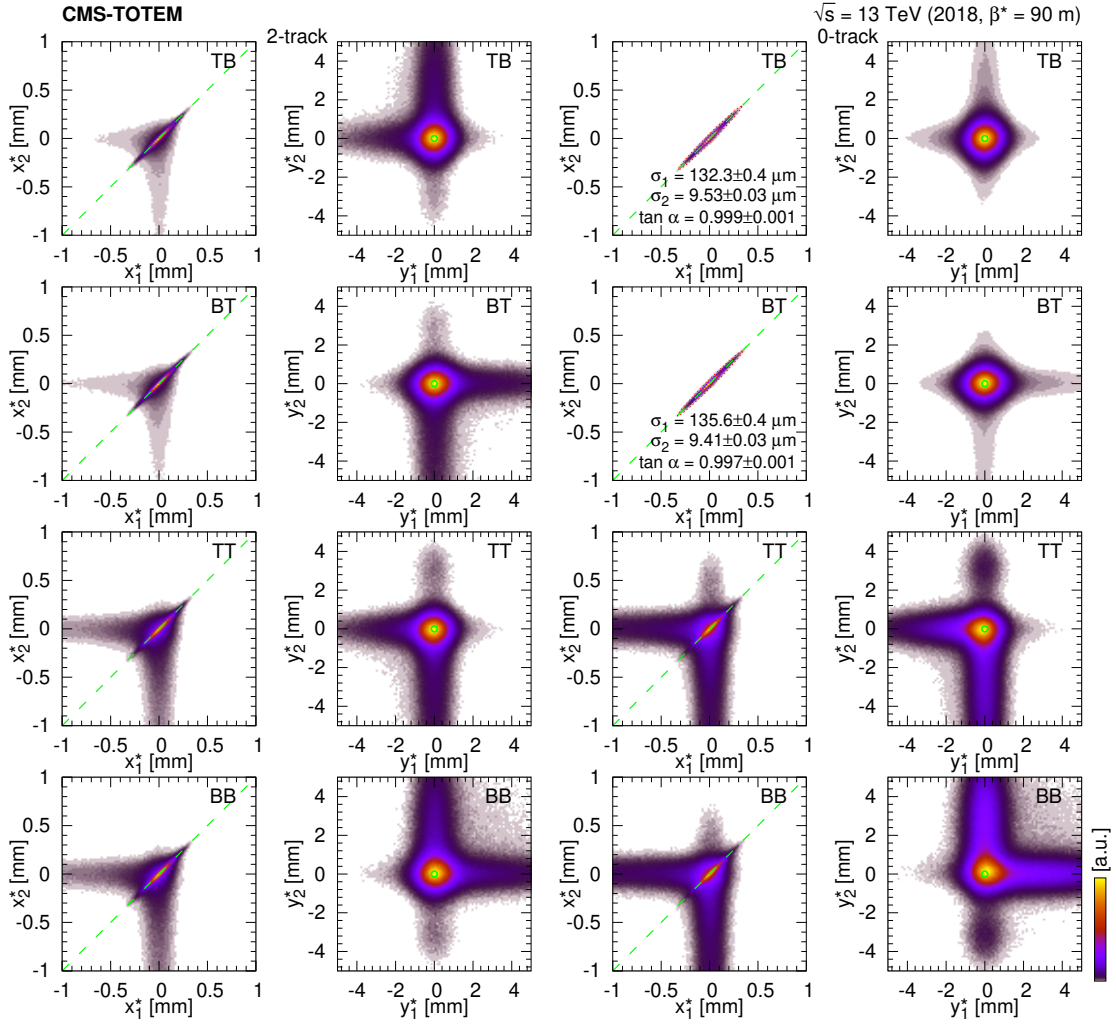


Figure 21. Joint distribution of x^* (or y^*) coordinates deduced using RPs in Arm 1 and 2 (subscripts 1 and 2), shown for various trigger configurations (TB, BT, TT, and BB, in rows). The two columns on the left side refer to the 2-track data set, whereas the two on the right side display distributions based on the 0-track data set. In the case of the diagonally triggered (TB and BT) 0-track (in part elastic) events the parameters (standard deviations in major and minor axis directions σ_1 and σ_2 , and the rotation angle α) of the fitted ellipses are displayed in the plots. The green circles mark (0,0), the dashed green lines are the identity lines.

study advanced methods for track reconstruction, measurements of strip-level detection efficiencies, cross-checks of beam optics, and the detector alignment procedure are presented, along with their application in the selection of signal events.

The track reconstruction is performed by finding a common polygonal area in the intercept-slope plane, thus exploiting all available cluster information. As a result, an ultimate spatial resolution of $6\text{--}7 \mu\text{m}$ is achieved, which is an order of magnitude smaller than the strip width. The tool is applied to the relative alignment of detector layers with μm precision. A tag-and-probe method is used to extract strip-level detection efficiencies. They are mostly high and constant, but for some strips they change with time; there are up to 20% variations. The tracklet efficiencies are calculated using a probabilistic model, based on the temporal variation of the hit detection efficiencies. These

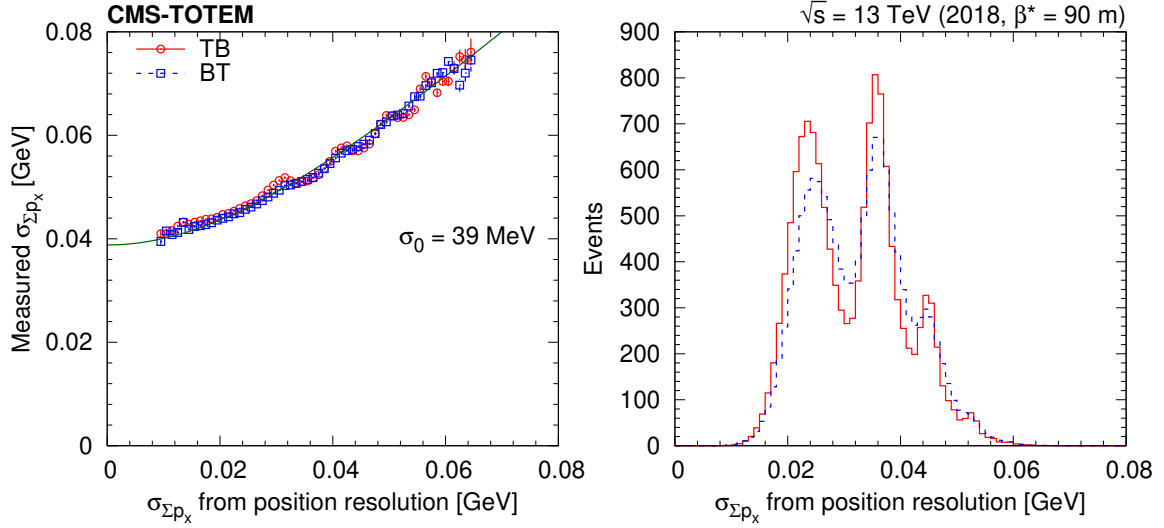


Figure 22. Left: Standard deviation of the momentum sum Σp_x for the 0-track data (TB and BT configurations), as a function of the predicted standard deviation from the RP position resolution. Statistical uncertainties are shown with vertical bars. A fit using the functional form $(\sigma_0^2 + \sigma_{\Sigma p_x}^2)^{1/2}$ is plotted with a green curve. Right: The occurrence of $\sigma_{\Sigma p_x}$. The peaks correspond to events with protons causing one or more two-strip clusters, and hence better resolution.

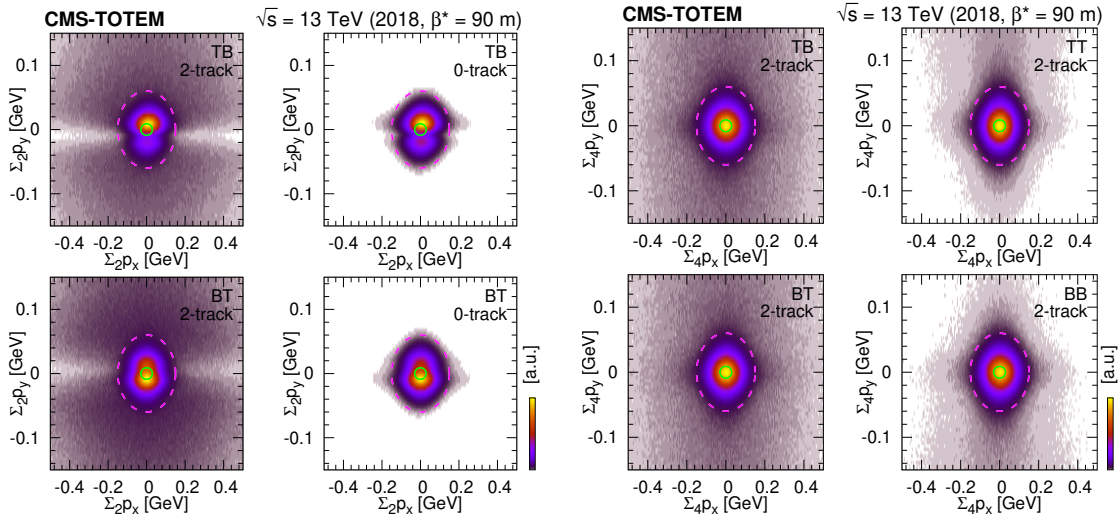


Figure 23. Left: Distribution of the sum of scattered proton momenta ($\Sigma_2 p_x, \Sigma_2 p_y$) for diagonally triggered events (TB and BT). The left column refers to the 2-track data set, whereas the right one displays the distribution based on the 0-track data set. Right: Distribution of the sum of scattered proton and central hadron momenta ($\Sigma_4 p_x, \Sigma_4 p_y$) shown for various trigger configurations (TB, BT, TT, and BB) for 2-track events. Ellipses with semi-minor axes of 150 MeV (x) and 60 MeV (y) are overlaid. The green circles mark (0, 0).

are functions of the tracklet location and slope. There are up to 50% losses in specific but small areas, to be corrected in the physics analyses.

The alignment of the Roman pot system (8 numbers for each arm) is performed by means of 16 measured quantities in the horizontal, and 12 in the vertical direction, resulting in a position accuracy of 3 μm in the horizontal and 60 μm in the vertical directions. The deduced locations

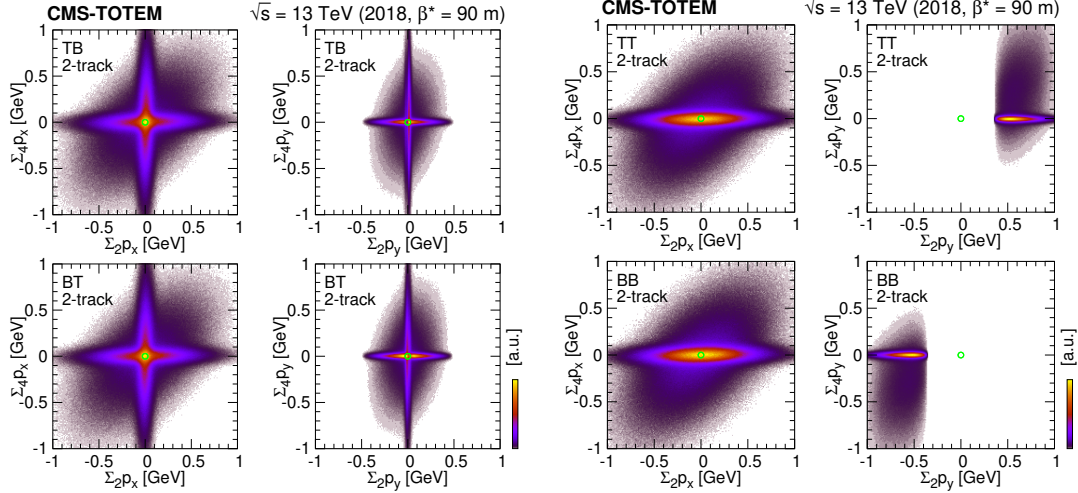


Figure 24. Distribution of the sum of scattered proton and central hadron momenta and the sum of scattered proton momenta only ($\Sigma_4 p_x$ and $\Sigma_2 p_x$, $\Sigma_4 p_y$ and $\Sigma_2 p_y$) shown for various trigger configurations (TB, BT, TT, and BB) for 2-track events. The green circles mark (0, 0).

of the primary interaction, the distribution of the scattered proton momenta, and their correlations confirm the success of the detailed calibration process and provide a solid ground for exclusive physics analyses based on the high- β^* data set. The developed methods have been successfully applied in the analysis of central exclusive production events [3].

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Data availability. Release and preservation of data used by the CMS Collaboration as the basis for publications is guided by the [CMS data preservation, re-use and open access policy](#).

Code availability. The CMS core software is publicly available on [GitHub](#)

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